

Numerisches Praktikum – Numerical Practical Training

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Ordinary Differential Equations

Return by 9:15 a.m. tomorrow

Free Training

- Write a program code for solving a system of 1st order ordinary differential equations of the type $\mathbf{y}' \equiv d\mathbf{y}/dx = f(\mathbf{y}, x)$ using the
 1. Euler forward method
 2. Runge-Kutta 2nd order (RK2): i.e. Midpoint Rule:

$$k_1 = hf(x_n, y_n) \quad (1)$$

$$k_2 = hf\left(x_n + \frac{1}{2}h, y_n + \frac{1}{2}k_1\right) \quad (2)$$

$$y_{n+1} = y_n + k_2 + O(h^3) \quad (3)$$

with a constant integration step h , as presented in the lecture.

Assignment for the Afternoon / Homework

- **Exercise.1, 8 points:** Accuracy and precision.
Solve the differential equation $y' = \exp(x)$ using both the Euler and the RK2 scheme. Start with the initial values $x = 0$ and $y(0) = 1$ and integrate up to $x = 1$ with constant integration steps $h = 1, 1/2, 1/3 \dots 1/10$. Plot y_i as a function of x_i and compare the results directly with the analytical solution. Plot the absolute true error for $x = 1$ as a function of h in a double logarithmic plot. Confirm the order of the integration scheme.
- **Exercise 2, 6 points:** Harmonic oscillator.
Solve the 2nd order ordinary differential equation (ODE) of a harmonic oscillator:

$$\ddot{x} \equiv \frac{d^2x}{d\tau^2} = -kx, \quad (4)$$

with $k = 16$. For this, first transform the 2nd order ODE to a set of two 1st order ODE's as shown in the lecture, i.e.:

$$k_{11} = dtf(t_n, v_n) \quad (5)$$

$$k_{12} = dt f(t_n, x_n) \quad (6)$$

$$k_{21} = dt f\left(t_n + \frac{1}{2}dt, v_n + \frac{1}{2}k_{12}, \dots\right) \quad (7)$$

$$k_{22} = dt f\left(t_n + \frac{1}{2}dt, x_n + \frac{1}{2}k_{11}, \dots\right) \quad (8)$$

$$x_{n+1} = x_n + k_{21} + O(dt^3) \quad (9)$$

$$v_{n+1} = v_n + k_{22} + O(dt^3) \quad (10)$$

Start with the initial values $\tau = 0$, $x(0) = 0.8$ and $\dot{x}(0) = 0$ and integrate the system for several periods using the RK2. Find an integration step dt that conserves the energy $E = \frac{1}{2}kA^2$, where A is the amplitude of the oscillation, with a relative true error of less than 0.01 at the end of the integration. Plot the results of $x(\tau)$ and $\dot{x}(\tau)$. Using the same integration step, how does the solution change when switching to the Euler scheme?

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• **Exercise 3, 6 points:** Volterra-Lotka System

Solve with your RK2 program the dimensionless coupled differential equation of the Volterra-Lotka system (see lecture):

$$\begin{aligned} \dot{u}_1 &= u_1(1 - u_2) \\ \dot{u}_2 &= \alpha u_2(u_1 - 1) \end{aligned}$$

with $\alpha = 0.5$, $u_1(0) = 1$ and $u_2(0) = 2, 3, 4$ and 5 from $\tau = 0$ to (at least) $\tau = 50$. Plot the solution of $u_1(\tau)$ and $u_2(\tau)$, e.g., for $u_2(0) = 3$. Find an appropriate timestep h for the integration. Is there a conserved quantity of the dynamical system? Also plot $u_2(\tau)$ versus $u_1(\tau)$.