### Numerisches Praktikum – Numerical Practical Training

#### **Hubert Klahr**

#### **Ordinary Differential Equations**

Return by 9:15 a.m. Feb 22nd as .pdf by Mail to: cecil@mpia.de

#### Free Training

- Write a program code for solving a system of 1st order ordinary differential equations of the type  $\mathbf{y}' \equiv d\mathbf{y}/dx = f(\mathbf{y}, x)$  using the
  - 1. Euler forward method
  - 2. Runge-Kutta 2nd order (RK2): i.e. Midpoint Rule:

$$k_1 = hf(x_n, y_n) \tag{1}$$

$$k_2 = hf\left(x_n + \frac{1}{2}h, y_n + \frac{1}{2}k_1\right)$$
 (2)

$$y_{n+1} = y_n + k_2 + O(h^3) (3)$$

with a constant integration step h, as presented in the lecture.

## Assignment for the Afternoon / Homework

- Exercise.1, 8 points: Accuracy and precision. Solve the differential equation  $y' = \exp(x)$  using both the Euler and the RK2 scheme. Start with the initial values x = 0 and y(0) = 1 and integrate up to x = 1 with constant integration steps  $h = 1, 1/2, 1/3 \dots 1/10$ . Plot  $y_i$  as a function of  $x_i$  and compare the results directly with the analytical solution. Plot the absolute true error for x = 1 as a function of h in a double logarithmic plot. Confirm the order of the integration scheme.
- Exercise 2, 6 points: Harmonic oscillator. Solve the 2<sup>nd</sup> order ordinary differential equation (ODE) of a harmonic oscillator:

$$\ddot{x} \equiv \frac{d^2x}{d\tau^2} = -kx,\tag{4}$$

with k = 16. For this, first transform the 2<sup>nd</sup> order ODE to a set of two 1<sup>st</sup> order ODE's as shown in the lecture, i.e.:

$$k_{11} = \operatorname{dt} f(t_n, v_n) \tag{5}$$

$$k_{12} = \operatorname{dt} f(t_n, x_n) \tag{6}$$

$$k_{21} = \operatorname{dt} f\left(t_n + \frac{1}{2}dt, v_n + \frac{1}{2}k_{12}, \ldots\right)$$
 (7)

$$k_{22} = \operatorname{dt} f\left(t_n + \frac{1}{2}dt, x_n + \frac{1}{2}k_{11}, \ldots\right)$$
 (8)

$$x_{n+1} = x_n + k_{21} + O(dt^3) (9)$$

$$v_{n+1} = v_n + k_{22} + O(dt^3) (10)$$

Start with the initial values  $\tau=0$ , x(0)=0.8 and  $\dot{x}(0)=0$  and integrate the system for several periods using the RK2. Find an integration step dt that conserves the energy  $E=\frac{1}{2}kA^2$ , where A is the amplitude of the oscillation, with a relative true error of less than 0.01 at the end of the integration. Plot the results of  $x(\tau)$  and  $\dot{x}(\tau)$ . Using the same integration step, how does the solution change when switching to the Euler scheme?

# • Exercise 3, 6 points: Volterra-Lotka System

Solve with your RK2 program the dimensionless coupled differential equation of the Volterra-Lotka system (see lecture):

$$\dot{u}_1 = u_1(1 - u_2)$$
  
 $\dot{u}_2 = \alpha u_2(u_1 - 1)$ 

with  $\alpha = 0.5$ ,  $u_1(0) = 1$  and  $u_2(0) = 2, 3, 4$  and 5 from  $\tau = 0$  to (at least)  $\tau = 50$ . Plot the solution of  $u_1(\tau)$  and  $u_2(\tau)$ , e.g., for  $u_2(0) = 3$ . Find an appropriate timestep h for the integration. Is there a conserved quantity of the dynamical system? Also plot  $u_2(\tau)$  versus  $u_1(\tau)$ .