

geirs2Panic
Richard J. Mathar

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Member GeirsPanic::exec (bool doTrim, bool doMimax, double north, bool doflip, bool doaltaz, bool doGeo, bool verbose, bool remov)

Divert windows into header units instead inserting the gaps into the single image.

Author

Richard J. Mathar

Member Histo::init (const valarray< float > &arr, const int Nbin, const double range[])

Check that Nbin is larger than zero etc.

Since

2013-01-28

2013-02-22 percentiles added

2013-06-07 NaN's ignored.

2013-12-04 cumulative bins added

Author

Richard J. Mathar

Member Histos::init (vector< valarray< float > > &arr, const int Nbin, const double *range, vector< string > &iname)

Check that Nbin is larger than zero etc.

Since

2013-01-28

Author

Richard J. Mathar

Member PixImage::apply (const RotTrans2D &rt) const

Carry over NaN pixel values (BLANK) to the result.

Since

2013-07-06

2 Hierarchical Index**2.1 Class Hierarchy**

This inheritance list is sorted roughly, but not completely, alphabetically:

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FitsImg2Asc	10
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3 Class Index

3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

Bbox2D	
A 2-dimensional rectangular boundary box parallel to the two Cartesian axes	4
Circle2D	
A circle represented by center point coordinate and radius	7
FitsImg2Asc	10
GeirsPanic	13
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Line2D	
An oriented line section represented by the 2-dimensional coordinates of starting and terminating point	26
PixImage	
A rectangular 2-dimensional array of pixels with individual values	28
Point2D	
A point with 2 coordinates represented in a Cartesian coordinate system	32
RotTrans2D	
A rotation followed by a translation	37

Square2D	
A square represented by the four vertices of the corners	40
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4 File Index

4.1 File List

Here is a list of all files with brief descriptions:

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fitsImg2Asc.cxx	
The program fitsImg2Asc converts the image in the primary HDU of a FITS file to an ASCII format	65
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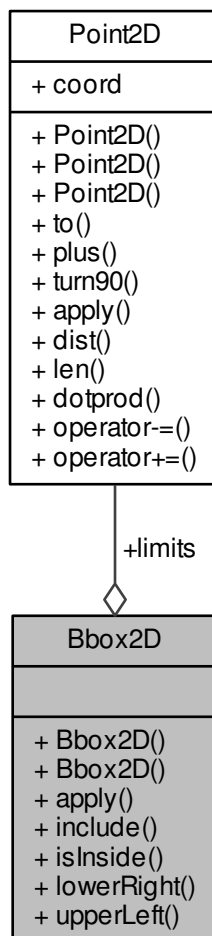
5 Class Documentation

5.1 Bbox2D Class Reference

A 2-dimensional rectangular boundary box parallel to the two Cartesian axes.

```
#include <Bbox2D.h>
```


Collaboration diagram for Bbox2D:



Public Member Functions

- `Bbox2D` (const [Point2D](#) &ptll, const [Point2D](#) &ptur)
Create a boundary box given two corner points.
- `Bbox2D` ()
- `Bbox2D apply` (const [RotTrans2D](#) &rt) const
Compute the bounding box of the quadrangle that is rotated-translated.
- void `include` (const [Point2D](#) &pt)
- bool `isInside` (const [Point2D](#) &pt) const
- [Point2D](#) `lowerRight` () const
- [Point2D](#) `upperLeft` () const

Public Attributes

- [Point2D](#) `limits` [2]
The two points at the lower left and upper right corner.

5.1.1 Detailed Description

A 2-dimensional rectangular boundary box parallel to the two Cartesian axes.

Since

2013-07-04

Author

Richard J. Mathar

5.1.2 Constructor & Destructor Documentation

5.1.2.1 Bbox2D::Bbox2D (const Point2D & *pt1*, const Point2D & *pt2*)

Create a boundary box given two corner points.

Parameters

<i>pt1</i>	The first corner.
<i>pt2</i>	The second corner.

5.1.2.2 Bbox2D::Bbox2D ()

Create an invalid bounding box. Default ctor.

5.1.3 Member Function Documentation

5.1.3.1 Bbox2D Bbox2D::apply (const RotTrans2D & *rt*) const

Compute the bounding box of the quadrangle that is rotated-translated.

Parameters

<i>in</i>	<i>rt</i>	The rotation-translation to be applied
-----------	-----------	--

Returns

The bounding box which includes all 4 rotated corner points of this bounding box.

5.1.3.2 void Bbox2D::include (const Point2D & *pt*)

Extend the bounding box such that a point is inside.

Parameters

<i>in</i>	<i>pt</i>	The point that may expand the bounding box.
-----------	-----------	---

5.1.3.3 bool Bbox2D::isInside (const Point2D & *pt*) const

Decide whether a point is inside (or on the rim) of the bounding box.

Parameters

<code>in</code>	<code>pt</code>	The point to be tested for insidedness.
-----------------	-----------------	---

Returns

True if the point is inside.

5.1.3.4 Point2D Bbox2D::lowerRight () const

Compute the lower right corner of the bounding box.

Returns

The point in the bounding box with maximum x and minimum y coordinate.

5.1.3.5 Point2D Bbox2D::upperLeft () const

Compute the upper left corner of the bounding box.

Returns

The point in the bounding box with minimum x and maximum y coordinate.

5.1.4 Member Data Documentation**5.1.4.1 Point2D Bbox2D::limits[2]**

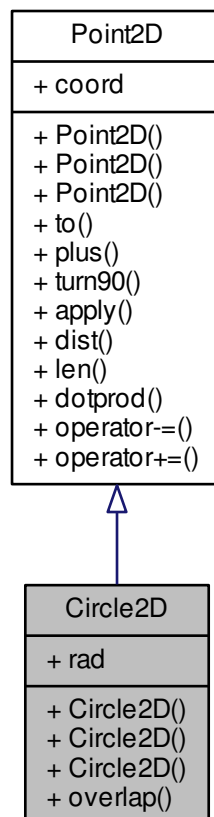
The two points at the lower left and upper right corner.

5.2 Circle2D Class Reference

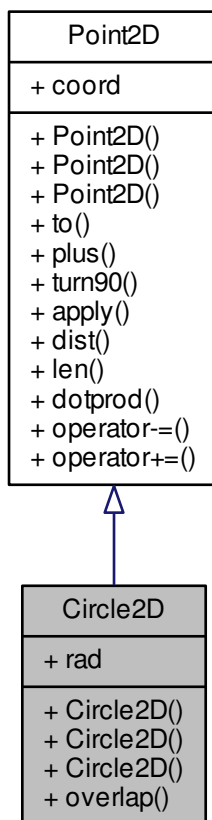
A circle represented by center point coordinate and radius.

```
#include <Circle2D.h>
```

Inheritance diagram for Circle2D:



Collaboration diagram for Circle2D:



Public Member Functions

- [Circle2D](#) (double x, double y, double r)
- [Circle2D](#) (const [Point2D](#) ctr, double r)
- [Circle2D](#) ()
- bool [overlap](#) (const [Circle2D](#) &oth) const

Public Attributes

- double [rad](#)
The radius.

5.2.1 Detailed Description

A circle represented by center point coordinate and radius.

Since

2013-07-03

Author

Richard J. Mathar

5.2.2 Constructor & Destructor Documentation**5.2.2.1 Circle2D::Circle2D (double *x*, double *y*, double *r*)**

Create a circle given its Cartesian coordinates of the center and radius.

Parameters

<i>x</i>	The x coordinate of the center.
<i>y</i>	The y coordinat of the centere
<i>r</i>	The radius.

5.2.2.2 Circle2D::Circle2D (const Point2D *ctr*, double *r*)

Create a circle given the mid point and the radius.

Parameters

<i>ctr</i>	The center point of the cricle.
<i>r</i>	The radius of the circle.

5.2.2.3 Circle2D::Circle2D ()

Create a circle of zero radius at the origin of coordinates.

5.2.3 Member Function Documentation**5.2.3.1 bool Circle2D::overlap (const Circle2D & *oth*) const**

Check whether this circle overlaps with another one.

Parameters

<i>oth</i>	The companion circle which may intersect this one.
------------	--

Returns

True if the circles overlap. False if they don't overlap or touch only at a point.

5.2.4 Member Data Documentation**5.2.4.1 double Circle2D::rad**

The radius.

5.3 FitsImg2Asc Class Reference

#include <FitsImg2Asc.h>

Collaboration diagram for FitsImg2Asc:

FitsImg2Asc
+ iname
+ FitsImg2Asc() + FitsImg2Asc() + ~FitsImg2Asc() + dump() + dump() + dump() + histo() + badMask()

Public Member Functions

- [FitsImg2Asc](#) (char *fitsInname)
Constructor.
- [FitsImg2Asc](#) (int argc, char *fitsInname[])
Constructor.
- [~FitsImg2Asc](#) ()
Destructor.
- void [dump](#) ()
Dump the entire image in ASCII style to cout.
- void [dump](#) (int range[4], FITS *ifits)
Dump the image in ASCII style to cout.
- void [dump](#) (string range)
Dump the image in ASCII style to cout.
- void [histo](#) (int Nbin, double range[2], string detsize, const bool doLogHist, const string epsout, const string txtout)
Generate a gnuplot X11 window with the histogram(s).
- void [badMask](#) (double range[2], string detsize, const string fitsout, int flipxy, string txtout, bool iraf)
Generate a FITS file with a bad mask of pixels.

Public Attributes

- vector< string > [iname](#)
Name of the input file.

5.3.1 Detailed Description

Since

2012-11-25

Author

Richard J. Mathar

5.3.2 Constructor & Destructor Documentation**5.3.2.1 FitsImg2Asc::FitsImg2Asc (char * *fitsName*)**

Constructor.

Parameters

<i>in</i>	<i>fitsName</i>	The name of the FITS file to be read.
-----------	-----------------	---------------------------------------

Since

2012-11-25

Author

Richard J. Mathar

5.3.2.2 FitsImg2Asc::FitsImg2Asc (int *argc*, char * *fitsName*[])

Constructor.

Parameters

<i>in</i>	<i>fitsName</i>	The names of the FITS file to be read.
-----------	-----------------	--

Since

2013-01-29

Author

Richard J. Mathar

5.3.2.3 FitsImg2Asc::~~FitsImg2Asc ()

Destructor.

5.3.3 Member Function Documentation**5.3.3.1 void FitsImg2Asc::dump ()**

Dump the entire image in ASCII style to cout.

5.3.3.2 void FitsImg2Asc::dump (int *range*[4], FITS * *ifits*)

Dump the image in ASCII style to cout.

Parameters

<i>in</i>	<i>range</i>	Four values denoting the pixel range. The lower value of x, the upper value of x (exclusive), the lower value of y and the upper value of y (exclusive) of the pixel region to be plotted.
-----------	--------------	--

5.3.3.3 void FitsImg2Asc::dump (string *range*)

Dump the image in ASCII style to cout.

Parameters

<i>in</i>	<i>range</i>	Four values denoting the lower value of x, the upper value of x (exclusive), the lower value of y and the upper value of y (exclusive) of the pixel region to be plottet.
-----------	--------------	---

5.3.3.4 `void FitsImg2Asc::histo (int Nbin, double range[2], string detsize, const bool doLogHist, const string epsout, const string txtout)`

Generate a gnuplot X11 window with the histogram(s).

Parameters

<i>in</i>	<i>Nbin</i>	The number of bins in the histogram. A value less than zero will trigger default setting of Nbin by the program. The actual number will then be the square root of the maximum number of data values in any of the arrays.
<i>in</i>	<i>range</i>	The lower [0] and upper [1] limit of the points on the horizontal axis (ADU) to be used.
<i>in</i>	<i>detsize</i>	A string of the form [xmin:xmax,ymin:ymax] selecting a XY ranges of pixels. If empty, the entire frame is examined.
<i>in</i>	<i>doLogHist</i>	Print a logarithmic, not a linear vertical scale.
<i>in</i>	<i>epsout</i>	If not an empty string, use this file for plotting, not the X11 screen.
<i>in</i>	<i>txtout</i>	If not an empty string, use this text file to store the histogram, not the X11 screen.

Since

2013-01-29

5.3.3.5 `void FitsImg2Asc::badMask (double range[2], string detsize, const string fitsout, int flipxy, string txtout, bool iraf)`

Generate a FITS file with a bad mask of pixels.

Parameters

<i>in</i>	<i>range</i>	The lower [0] and upper [1] limit of the points on the horizontal axis (ADU) to be used.
<i>in</i>	<i>detsize</i>	A string of the form [xmin:xmax,ymin:ymax] selecting a XY ranges of pixels. If empty, the entire frame is examined.
<i>in</i>	<i>fitsout</i>	Name of the FITS output file.
<i>in</i>	<i>flipxy</i>	If the LSB bit (bit 0) is set, flip along x coordinate. If the bit 1 is set, flip along y coordinate.
<i>in</i>	<i>txtout</i>	Name of the file with the GEIRS specific list of bad pixels. Not used if null or an empty file name.

Since

2013-12-04

5.3.4 Member Data Documentation

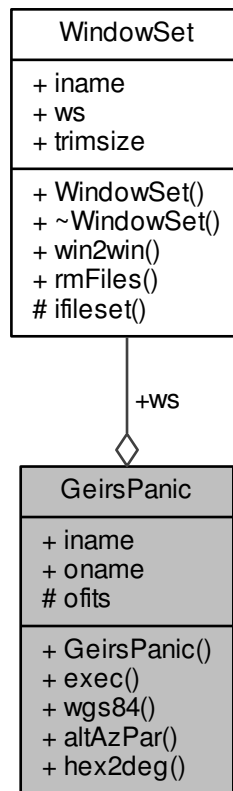
5.3.4.1 `vector<string> FitsImg2Asc::iname`

Name of the input file.

5.4 GeirsPanic Class Reference

```
#include <GeirsPanic.h>
```

Collaboration diagram for GeirsPanic:



Public Member Functions

- [GeirsPanic](#) (char *fitsInname, const char *fitsOutname, int gap, int chpsz)
- void [exec](#) (bool doTrim, bool doMimax, double north, bool doflip, bool doaltaz, bool doGeo, bool verbose, bool remov)

Modify the FITS header and optionally rotate/flip the image.

Static Public Member Functions

- static void [wgs84](#) (const double lolatlat[3], double xyz[3])
Convert geographic longitude, latitude and sea level to geocentric Cartesian coords.
- static void [altAzPar](#) (double ha, double dec, double phi, double aap[3])
Derive altitude (complementary zenith), azimuth and paralactic angle.
- static double [hex2deg](#) (const string &hexstr, bool isdeg)
Convert a sedecimal-String to degrees.

Public Attributes

- string [iname](#)
Name of the input file.

- string `oname`
Name of the output file.
- `WindowSet ws`
The set of subwindows.

Protected Attributes

- `FITS * ofits`
The FITS file that will be created.

5.4.1 Detailed Description

Since

2012-10-23

Author

Richard J. Mathar

5.4.2 Constructor & Destructor Documentation

5.4.2.1 `GeirsPanic::GeirsPanic (char * fitsName, const char * fitsOname, int gap, int chpsz)`

Parameters

<code>in</code>	<code>fitsname</code>	The name of the FITS file to be read.
<code>in</code>	<code>fitspl</code>	The name of the FITS file to be created. This may be the empty string ("") indicating that the file name is to be determined with a standard rule.
<code>in</code>	<code>gap</code>	The gap between the chips of the mosaic in units of pixels.
<code>in</code>	<code>chpsz</code>	The edge length of the single chip in pixel units. This would be 2048 for Hawaii2 and Hawaii2-RG, or 1024 for Hawaii1.

Since

2012-10-23

Author

Richard J. Mathar

5.4.3 Member Function Documentation

5.4.3.1 `void GeirsPanic::exec (bool doTrim, bool doMimax, double north, bool doflip, bool doaltaz, bool doGeo, bool verbose, bool remov)`

Modify the FITS header and optionally rotate/flip the image.

Parameters

<code>in</code>	<code>doTrim</code>	If true, remove (blanken) the 4 pixels at the edges of each detector.
<code>in</code>	<code>doMimax</code>	If true, write DATAMIN, DATAMAX, DATAMED etc to the header.

in	<i>gap</i>	The size of the crossing gap (pixels) in the mosaic.
in	<i>chpsz</i>	The size of a single chip (pixels) of the mosaic.
in	<i>north</i>	The direction angle of North in the current image (+90=up, +180 = left)
in	<i>doflip</i>	If true, flip the image. The main idea is to trigger a swap of the Eastern side relative to North, if previously found to be wrong. There is of course an effect of this option on the direction of North in the final image, unless this was exactly +90 or -90.
in	<i>doaltaz</i>	If true, derive ALT, AZ and PARANG from latitude, HA and DEC. Warning: this will only produce correct values if the keywords HA, DEC and GEOPOS_L are degrees in the original header, or HA and DEC are given in hex-decimal colon-separated notation.
in	<i>doGeo</i>	If true, add OBSGEO-[XYZ] to the keywords.
in	<i>verbose</i>	If true, write more verbose output.
in	<i>remov</i>	If true, the initial file (or the initial file set if windowed) is removed on exit. This is always done if requested, and may lead to loss of data if anything is wrong with the new file that is created.

Since

2012-10-18

Todo Divert windows into header units instead inserting the gaps into the single image.

Author

Richard J. Mathar

If any keywords were changed or added, write a HISTORY line keeping track of the template file, and remove the CHECKSUM keyword if present.

5.4.3.2 `void GeirsPanic::wgs84 (const double lolat[3], double xyz[3]) [static]`

Convert geographic longitude, latitude and sea level to geocentric Cartesian coords.

Parameters

in	<i>lolat</i>	The longitude (lambda, degrees), latitude (phi, degrees) and altitude (meters) of the site. The latitude is the topocentric one, not the geocentric one.
out	<i>xyz</i>	The x, y and z coordinates in the Greenwich centered coordinates (meters).

Since

2012-10-25

5.4.3.3 `void GeirsPanic::altAzPar (double ha, double dec, double phi, double aap[3]) [static]`

Derive altitude (complementary zenith), azimuth and paralactic angle.

Note that this will fail (drastically) if any of the units in the original header for the hour angle (HA), declination (DEC) or latitude (OBSGEO-L) were not degrees.

Parameters

in	<i>ha</i>	Hour angle at the epoch (deg)
in	<i>dec</i>	Declination at the epoch (deg).
in	<i>phi</i>	Observer's latitude (deg).

out	<i>aap</i>	The altitude (deg), azimuth (deg, South to West) and parallactic angle (deg)
-----	------------	--

Since

2012-10-25

5.4.3.4 double GeirsPanic::hex2deg (const string & *hexstr*, bool *isdeg*) [static]

Convert a sedecimal-String to degrees.

Parameters

in	<i>hexstr</i>	A string with optional sign, integer number, colon, integer number, colon and integer or floating point number.
in	<i>isdeg</i>	If true, assume that the string is in DD:MM:SS.ss format. If false the string is in HH:MM:SS.ss format. This implies an additional factor 15 to move on to degrees. If the string contains a sign (plus or minus), this parameter is ignored and the function assumes degrees.

Returns

The value in degrees.

Since

2012-11-13

5.4.4 Member Data Documentation**5.4.4.1 string GeirsPanic::iname**

Name of the input file.

This may also be the stem of the window set, without the `_win*.fits`.**5.4.4.2 string GeirsPanic::oname**

Name of the output file.

5.4.4.3 WindowSet GeirsPanic::ws

The set of subwindows.

This may be a simple single full frame.

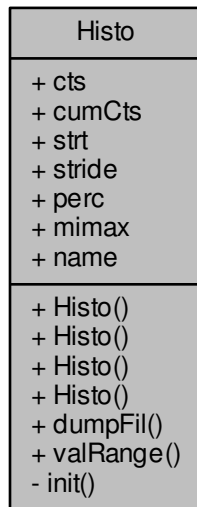
5.4.4.4 FITS* GeirsPanic::ofits [protected]

The FITS file that will be created.

5.5 Histo Class Reference

#include <Histo.h>

Collaboration diagram for Histo:



Public Member Functions

- [Histo](#) ()

Constructor.

- [Histo](#) (const valarray< float > &arr, const int Nbin, const double range[], string &nam)
- [Histo](#) (const valarray< float > &arr, const int Nbin, string &nam)

Constructor.

- [Histo](#) (const valarray< float > &arr, string &nam)

Constructor.

- void [dumpFil](#) (const char *fname)

Create the bins in xy gnuplot format. For each number in the histogram, a short horizontal line is produced, such that concatenation of these horizontal lines with straight line segments produces a step function along the x axis.

Static Public Member Functions

- static int [valRange](#) (const valarray< float > &arr, double [mimax](#)[2])

Determine smallest and largest value in all elements of the array.

Public Attributes

- vector< int > [cts](#)

The counts on a per-bin basis.

- vector< int > [cumCts](#)

The cumulative counts on a per-bin basis.

- double [strf](#)

The smallest range of the first bin.

- double [stride](#)

The width of each bin.

- double `perc` [7]

Percentile abscissas.

- double `mimax` [3]

Minimum and maximum value and arithmetic mean.

- string `name`

Some kind of file name or tag attached to this statistics.

Private Member Functions

- void `init` (const valarray< float > &arr, const int Nbin, const double range[])

Principal part of the constructor.

5.5.1 Detailed Description

Since

2013-01-29

Author

Richard J. Mathar

5.5.2 Constructor & Destructor Documentation

5.5.2.1 Histo::Histo ()

Constructor.

Empty histogram. The main purpose of this construction is to allow allocations of vectors of histograms.

Since

2013-01-28

Author

Richard J. Mathar

5.5.2.2 Histo::Histo (const valarray< float > &arr, const int Nbin, const double range[], string &nam)

5.5.2.3 Histo::Histo (const valarray< float > &arr, const int Nbin, string &nam)

Constructor.

The range of the bins is automatically set to reach out to the smallest and largest value in the array.

Parameters

<i>arr</i>	The array of values to be binned.
<i>Nbin</i>	The number of bins into which the values are split.

Since

2013-01-28

Author

Richard J. Mathar

5.5.2.4 `Histo::Histo (const valarray< float > & arr, string & nam)`

Constructor.

The number of bins is set equal to the square root of the number of values in the array. The range of the bins is automatically set to reach out to the smallest and largest value in the array.

Parameters

<i>arr</i>	The array of values to be binned.
------------	-----------------------------------

Since

2013-01-28

Author

Richard J. Mathar

5.5.3 Member Function Documentation

5.5.3.1 `int Histo::valRange (const valarray< float > & arr, double mimax[2]) [static]`

Determine smallest and largest value in all elements of the array.

NaN-values are not taken into account (ignored). In that sense, this function is an improvement relative to the undefined result if `min()` or `max()` of the array are taken as defined in the STL.

Parameters

<i>in</i>	<i>arr</i>	The array to be scanned.
<i>out</i>	<i>mimax</i>	The minimum in [0], the maximum in [1]. If the array does not contain values that are not NaN's, both values are unchanged.

Returns

The number of non-NaN's in the array.

Since

2013-06-07

5.5.3.2 `void Histo::dumpFil (const char * fname)`

Create the bins in xy gnuplot format. For each number in the histogram, a short horizontal line is produced, such that concatenation of these horizontal lines with straight line segments produces a step function along the x axis.

Parameters

<i>in</i>	<i>fname</i>	The file to be generated.
-----------	--------------	---------------------------

5.5.3.3 `void Histo::init (const valarray< float > & arr, const int Nbin, const double range[]) [private]`

Principal part of the constructor.

The statistics (minimum and maximum and the percentiles) is computed over the entire range of the `arr`-values that are not NaN's, not only over the values within the interval specified by the `range` argument.

Parameters

<i>arr</i>	The array of values to be binned.
<i>Nbin</i>	The number of bins into which the values are split.
<i>range</i>	The minimum and maximum value in the first and last bin.

Todo Check that Nbin is larger than zero etc.

Since

2013-01-28
 2013-02-22 percentiles added
 2013-06-07 NaN's ignored.
 2013-12-04 cumulative bins added

Author

Richard J. Mathar

5.5.4 Member Data Documentation

5.5.4.1 `vector<int> Histo::cts`

The counts on a per-bin basis.

Provides by its length an explicit count of the bins.

5.5.4.2 `vector<int> Histo::cumCts`

The cumulative counts on a per-bin basis.

`cumCts[i]` contains $\sum_{k=0..n} cts[k]$.

Since

2013-12-04

5.5.4.3 `double Histo::strt`

The smallest range of the first bin.

5.5.4.4 `double Histo::stride`

The width of each bin.

5.5.4.5 `double Histo::perc[7]`

Percentile abscissas.

[0] the 3 sigma level (left), [1] the 2 sigma left, [2] the 1 sigma left, [3] the median, [4] the 1 sigma right, [5] the 2 sigma right, [6] the 3 sigma right.

5.5.4.6 `double Histo::mimax[3]`

Minimum and maximum value and arithmetic mean.

Since

2013-06-07

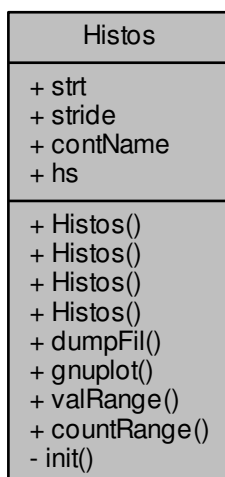
5.5.4.7 `string Histo::name`

Some kind of file name or tag attached to this statistics.

5.6 Histos Class Reference

```
#include <Histos.h>
```

Collaboration diagram for Histos:



Public Member Functions

- [Histos](#) ()
Constructor.
- [Histos](#) (vector< valarray< float > > &arr, vector< string > &iname)
Constructor.
- [Histos](#) (vector< valarray< float > > &arr, const int Nbin, vector< string > &iname, string &contName)
Constructor.
- [Histos](#) (vector< valarray< float > > &arr, const int Nbin, vector< string > &iname, string &contName, double range[2])
Constructor.
- void [dumpFil](#) (const char *fname)
Create ASCII file in xy gnuplot format.
- void [gnuplot](#) (const char *gplDfile, const char *gplfile, const bool doLogHist, string epsout)
Generate a gnuplot shell command list.

Static Public Member Functions

- static void [valRange](#) (vector< valarray< float > > &arr, double mimax[2])
Determine smallest and largest value in all elements of the arrays.
- static int [countRange](#) (vector< valarray< float > > &arr)

Public Attributes

- double `strt`
The smallest range of the first bin.
- double `stride`
The width of each bin.
- string `contName`
Some type of contents description.
- vector< `Histo` > `hs`

Private Member Functions

- void `init` (vector< valarray< float > > &arr, const int Nbin, const double *range, vector< string > &iname)
Principal part of the constructor.

5.6.1 Detailed Description**Since**

2013-01-29

Author

Richard J. Mathar

5.6.2 Constructor & Destructor Documentation**5.6.2.1 Histos::Histos ()**

Constructor.

Empty histogram. The main purpose of this construction is to allow allocations of vectors of histograms.

Since

2013-01-28

Author

Richard J. Mathar

5.6.2.2 Histos::Histos (vector< valarray< float > > & arr, vector< string > & iname)

Constructor.

Parameters

<i>arr</i>	The array of values to be binned.
<i>iname</i>	The associated list of names, one per arr component.

Since

2013-01-28

Author

Richard J. Mathar

5.6.2.3 Histos::Histos (vector< valarray< float > > & arr, const int Nbin, vector< string > & iname, string & conts)

Constructor.

Parameters

<i>arr</i>	The array of values to be binned.
<i>Nbin</i>	A number of bins to be used. If less than 1, the program depicts a default on its own.
<i>iname</i>	Name of the files associated with the arr.
<i>conts</i>	A global simple name for the entire collection. Mainly for use with display headers and the like.

Since

2013-01-28

Author

Richard J. Mathar

5.6.2.4 `Histos::Histos (vector< valarray< float > > & arr, const int Nbin, vector< string > & iname, string & conts, double range[2])`

Constructor.

Parameters

	<i>arr</i>	The array of values to be binned.
	<i>Nbin</i>	A number of bins to be used. If less than 1, the program depicts a default on its own.
	<i>iname</i>	Name of the files associated with the arr.
	<i>conts</i>	A global simple name for the entire collection. Mainly for use with display headers and the like.
<i>in</i>	<i>range</i>	

Since

2013-01-28

Author

Richard J. Mathar

5.6.3 Member Function Documentation

5.6.3.1 `void Histos::dumpFil (const char * fname)`

Create ASCII file in xy gnuplot format.

Parameters

<i>in</i>	<i>fname</i>	The file to be generated.
-----------	--------------	---------------------------

Since

2013-01-29

2013-12-04 cumulative sum column added.

Author

Richard J. Mathar

5.6.3.2 `void Histos::gnuplot (const char * fdname, const char * fpltname, const bool doLogHist, string epsout)`

Generate a gnuplot shell command list.

Parameters

in	<i>fdname</i>	The file that contains the data to be plotted.
in	<i>fplname</i>	The file with the gnuplot commands.
in	<i>doLogHist</i>	Print a logarithmic, not a linear vertical scale
in	<i>epsout</i>	Print diagram into the EPS file, not on screen.

Since

2013-01-29

Author

Richard J. Mathar

5.6.3.3 void Histos::valRange (vector< valarray< float > > & arr, double mimax[2]) [static]

Determine smallest and largest value in all elements of the arrays.

NaN-values are not taken into account (ignored).

Parameters

in	<i>arr</i>	The arrays to be scanned.
out	<i>mimax</i>	The minimum in [0], the maximum in [1] If the array arr has zero size, the mimax[] are unchanged on return.

5.6.3.4 int Histos::countRange (vector< valarray< float > > & arr) [static]

Parameters

in	<i>arr</i>	The arrays to be scanned.
----	------------	---------------------------

Returns

5.6.3.5 void Histos::init (vector< valarray< float > > & arr, const int Nbin, const double * range, vector< string > & iname) [private]

Principal part of the constructor.

Parameters

<i>arr</i>	The array of values to be binned.
<i>Nbin</i>	The number of bins into which the values are split.
<i>range</i>	The minimum and maximum value in the first and last bin.

Todo Check that Nbin is larger than zero etc.

Since

2013-01-28

Author

Richard J. Mathar

5.6.4 Member Data Documentation

5.6.4.1 double Histos::strt

The smallest range of the first bin.

5.6.4.2 double Histos::stride

The width of each bin.

5.6.4.3 string Histos::contName

Some type of contents description.

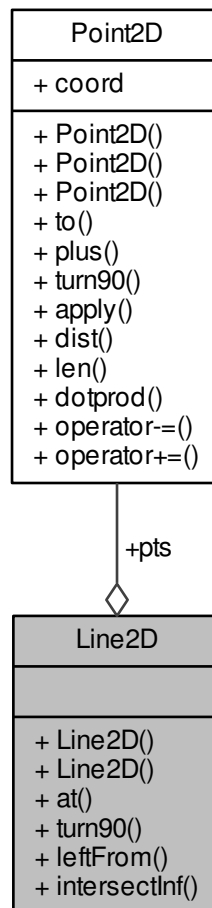
5.6.4.4 vector<Histo> Histos::hs

5.7 Line2D Class Reference

An oriented line section represented by the 2-dimensional coordinates of starting and terminating point.

```
#include <Line2D.h>
```

Collaboration diagram for Line2D:



Public Member Functions

- [Line2D](#) (const [Point2D](#) &strt, const [Point2D](#) &fini)
- [Line2D](#) ()

- [Point2D at](#) (double t) const
- [Point2D turn90](#) () const
- bool [leftFrom](#) (const [Point2D](#) &pt) const
- [Point2D intersectInf](#) (const [Line2D](#) &oth) const

Public Attributes

- [Point2D pts](#) [2]
The terminal points of start and end.

5.7.1 Detailed Description

An oriented line section represented by the 2-dimensional coordinates of starting and terminating point.

Since

2013-07-03

Author

Richard J. Mathar

5.7.2 Constructor & Destructor Documentation

5.7.2.1 [Line2D::Line2D](#) (const [Point2D](#) & *strt*, const [Point2D](#) & *fini*)

Create a line that connects two given points.

Parameters

<i>strt</i>	The starting point.
<i>fini</i>	The terminal point.

5.7.2.2 [Line2D::Line2D](#) ()

Create a line of zero length at the origin.

5.7.3 Member Function Documentation

5.7.3.1 [Point2D](#) [Line2D::at](#) (double *t*) const

Determine the point at line parameter t.

Parameters

<i>t</i>	The line parameter.
----------	---------------------

Returns

A point at distance t relative to the starting point. The point is the starting point if t=0 and the terminal point if t=1.

5.7.3.2 [Point2D](#) [Line2D::turn90](#) () const

Create a vector (i.e, a direction) with an orientation turned 90 degrees ccw.

5.7.3.3 [bool](#) [Line2D::leftFrom](#) (const [Point2D](#) & *pt*) const

Decide whether a point is to the left or to the right of the line (the line considered of infinite length)

Parameters

<i>pt</i>	The pivotal point.
-----------	--------------------

Returns

True if the point to the left or on the line.

5.7.3.4 Point2D Line2D::intersectInf (const Line2D & *oth*) const

Determine the point of intersection between this infinite line and another infinite line.

Parameters

<i>oth</i>	The other line (virtually extended both ways to infinity)
------------	---

Returns

The point of intersection.

5.7.4 Member Data Documentation

5.7.4.1 Point2D Line2D::pts[2]

The terminal points of start and end.

5.8 PixImage Class Reference

A rectangular 2-dimensional array of pixels with individual values.

```
#include <PixImage.h>
```

Collaboration diagram for PixImage:

PixImage
+ vals + rows + cols
+ PixImage() + PixImage() + PixImage() + ~PixImage() + operator Bbox2D() + toFits() + apply() + at() + idx() + hull()

Public Member Functions

- [Pixmap](#) (const int ncols, const int nrows)
Create an empty image with all values set to zero.
- [Pixmap](#) ()
Create an image of zero size (without pixels).
- [Pixmap](#) (FITS &fit, int slic=0)
Read the pixel values from a slice of a FITS cube.
- [~Pixmap](#) ()
- [operator Bbox2D](#) () const
Generate the bounding box of this pixel array.
- [FITS * toFits](#) (const char *foutname) const
Generate a FITS file with this image as the primary HDU.
- [Pixmap * apply](#) (const [RotTrans2D](#) &rt) const
- [double at](#) (const int row, const int col) const
Read/get the value of the intensity at a specific pixel.
- [int idx](#) (const int row, const int col) const
Obtain the flat index of a (x,y) pair of indices.
- [Square2D hull](#) (const [RotTrans2D](#) &rt, const int row, const int col, int idxReg[2][2], const [Bbox2D](#) &bbrot) const

Public Attributes

- [valarray< double > vals](#)
The values (intensities) within the pixels.
- [int rows](#)
Number of rows.
- [int cols](#)
Number of columns.

5.8.1 Detailed Description

A rectangular 2-dimensional array of pixels with individual values.

Since

2013-07-04

Author

Richard J. Mathar

5.8.2 Constructor & Destructor Documentation**5.8.2.1 Pixmap::Pixmap (const int *ncols*, const int *nrows*)**

Create an empty image with all values set to zero.

Parameters

<i>in</i>	<i>ncols</i>	The number of columns in the image. The same as the number of pixels along x.
<i>out</i>	<i>nrows</i>	The number of rows in the image. The same as the number of pixels along y.

5.8.2.2 `PixelImage::PixelImage ()`

Create an image of zero size (without pixels).

5.8.2.3 `PixelImage::PixelImage (FITS & fit, int slic = 0)`

Read the pixel values from a slice of a FITS cube.

Parameters

<i>fit</i>	The FITS object with at least one image plane in the Primary HDU.
<i>slic</i>	The 0-based index into the FITS cube.

5.8.2.4 `PixelImage::~~PixelImage ()`

Destructor. Release the allocated memory areas.

5.8.3 Member Function Documentation

5.8.3.1 `PixelImage::operator Bbox2D () const`

Generate the bounding box of this pixel array.

Returns

The quadrangular bounding box.

5.8.3.2 `FITS * PixelImage::toFits (const char * foutname) const`

Generate a FITS file with this image as the primary HDU.

Parameters

<i>in</i>	<i>foutname</i>
-----------	-----------------

Returns

The FITS file with a dummy header.

Since

2013-07-06

5.8.3.3 `PixelImage * PixelImage::apply (const RotTrans2D & rt) const`

Generate a quadrangle of pixels by rotation and translation of a indexed pixel.

Todo Carry over NaN pixel values (BLANK) to the result.

Since

2013-07-06

5.8.3.4 `double PixelImage::at (const int row, const int col) const`

Read/get the value of the intensity at a specific pixel.

Parameters

<i>in</i>	<i>row</i>	
<i>in</i>	<i>col</i>	

Returns

The current contents at that pixel

5.8.3.5 `int PixImage::idx (const int row, const int col) const`

Obtain the flat index of a (x,y) pair of indices.

Parameters

<i>in</i>	<i>row</i>	
<i>in</i>	<i>col</i>	

Returns

The 0-based index $col + (\text{number of columns}) * row$.

Since

2013-07-06

5.8.3.6 `Square2D PixImage::hull (const RotTrans2D & rt, const int row, const int col, int idxReg[2][2], const Bbox2D & bbrot) const`

Generate a hull (an encompassing integer rectangle) of the image of a pixel

Parameters

<i>in</i>	<i>rt</i>	The rotation-translation to be applied to the pixel.
<i>in</i>	<i>row</i>	The row index of the pixel.
<i>in</i>	<i>col</i>	The column index of the pixel.
<i>in</i>	<i>bbrot</i>	The boundary box of the rotated entire original array.
<i>out</i>	<i>idxReg</i>	The index region of the image of the pixel under the operation. <code>idxReg[0][0]</code> refers to the lower left corner, <code>idxReg[1][1]</code> to the upper right. <code>idxReg[][0]</code> refers to the x coordinates, <code>idxReg[][1]</code> to the y coordinates. <code>idx[1][1]</code> is non-include (as usual in C/C++/Java): The pixel (row,col) will cover parts of <code>idxReg[0][0]..idxReg[0][1]-1</code> along x and <code>idxReg[1][0]..idxReg[1][1]-1</code> along y after rotation.

Returns

The rotated pixel in the original coordinate system.

5.8.4 Member Data Documentation

5.8.4.1 `valarray<double> PixImage::vals`

The values (intensities) within the pixels.

5.8.4.2 `int PixImage::rows`

Number of rows.

5.8.4.3 `int PixImage::cols`

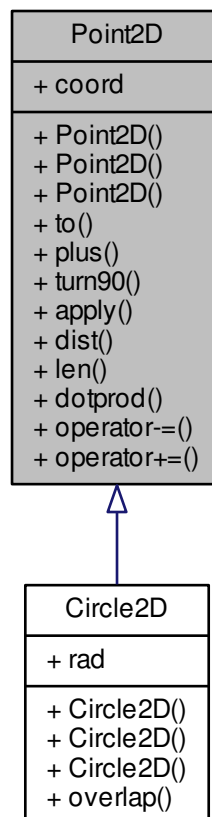
Number of columns.

5.9 Point2D Class Reference

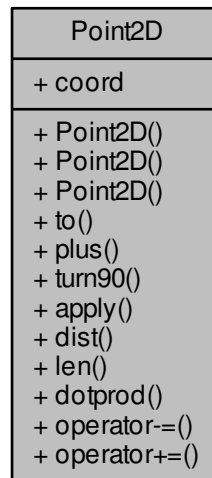
A point with 2 coordinates represented in a Cartesian coordinate system.

```
#include <Point2D.h>
```

Inheritance diagram for Point2D:



Collaboration diagram for Point2D:



Public Member Functions

- [Point2D](#) (double x, double y)
- [Point2D](#) (const double xandy[2])
- [Point2D](#) ()
- [Point2D to](#) (const [Point2D](#) &oth) const
- [Point2D plus](#) (const [Point2D](#) &oth) const
Add this point (as a vector) to another point.
- [Point2D turn90](#) () const
- [Point2D apply](#) (const [RotTrans2D](#) &rt) const
- double [dist](#) (const [Point2D](#) &oth) const
- double [len](#) () const
- double [dotprod](#) (const [Point2D](#) &oth) const
- [Point2D & operator-=-](#) (const [Point2D](#) &rhs)
Subtract another point, interpreting both points as vectors.
- [Point2D & operator+=](#) (const [Point2D](#) &rhs)
Add another point, interpreting both points as vectors.

Public Attributes

- double [coord](#) [2]
The two Cartesian coordinates x and y of the point.

5.9.1 Detailed Description

A point with 2 coordinates represented in a Cartesian coordinate system.

Since

2013-07-03

Author

Richard J. Mathar

5.9.2 Constructor & Destructor Documentation

5.9.2.1 Point2D::Point2D (double x, double y)

Create a point given its two Cartesian coordinates.

Parameters

<i>x</i>	The x coordinate.
<i>y</i>	The y coordinate

5.9.2.2 Point2D::Point2D (const double *xandy*[2])

Create a point given its coordinate vector.

Parameters

<i>xandy</i>	The x coordinate in [0], the y coordinate in [1].
--------------	---

5.9.2.3 Point2D::Point2D ()

Create a point at the origin of coordinates.

5.9.3 Member Function Documentation

5.9.3.1 Point2D Point2D::to (const Point2D & *oth*) const

Compute the direction from this point to another. Equivalent description would be to constructe the vector to the other point minus this.

Parameters

<i>oth</i>	The other point to connect this to.
------------	-------------------------------------

5.9.3.2 Point2D Point2D::plus (const Point2D & *oth*) const

Add this point (as a vector) to another point.

Parameters

<i>oth[in]</i>	The other point to attach this to.
----------------	------------------------------------

Returns

The point which has x and y coordinates which are sums of the x and y coordinates of this and oth.

5.9.3.3 Point2D Point2D::turn90 () const

Create a point that is rotated by 90 degrees ccw .

Returns

A point with coordinates (-y,+x) if this =(+x,+y).

5.9.3.4 Point2D Point2D::apply (const RotTrans2D & rt) const

Apply a rotation-translation to this point. The effect is the same as calling RotTrans2D::apply(const Point2D &).

Parameters

<i>in</i>	<i>rt</i>	The rotation-translation operator to be applied.
-----------	-----------	--

Returns

A point with coordinates rotated then translated by *rt*.

5.9.3.5 double Point2D::dist (const Point2D & oth) const

Compute the distance to another point.

Parameters

<i>oth</i>	The other reference point.
------------	----------------------------

Returns

The distance between this and *oth*. Square root of the sum of the squared differences in both Cartesian coordinates.

5.9.3.6 double Point2D::len () const

Compute the length of the vector from the origin to this point.

Returns

The distance between this and the origin.

5.9.3.7 double Point2D::dotprod (const Point2D & oth) const

Compute the dot product of this point (as a vector) with another.

Returns

The dot product $\text{this.x} * \text{oth.x} + \text{this.y} * \text{oth.y}$.

5.9.3.8 Point2D & Point2D::operator-= (const Point2D & rhs)

Subtract another point, interpreting both points as vectors.

Conceptionally this is (up to a sign flip or up to a role reversal) the same as the function `to(const Point2D &)`. So the same result would be obtained by the call `rhs.to(*this)`.

Parameters

<i>rhs</i>	The point to be subtracted.
------------	-----------------------------

Returns

A point where coordinates are individually reduced by those of *rhs*.

5.9.3.9 Point2D & Point2D::operator+= (const Point2D & rhs)

Add another point, interpreting both points as vectors.

Parameters

<i>rhs</i>	The point to be added.
------------	------------------------

Returns

A point where coordinates are individually extended by those of rhs.

5.9.4 Member Data Documentation

5.9.4.1 double Point2D::coord[2]

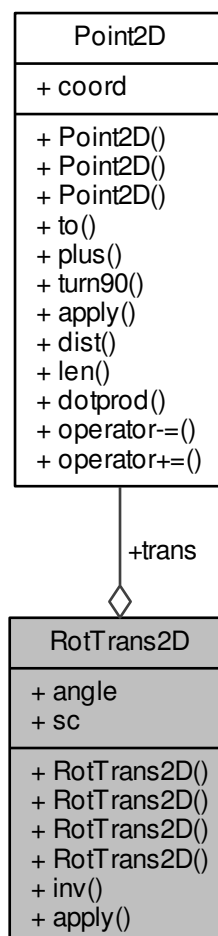
The two Cartesian coordinates x and y of the point.

5.10 RotTrans2D Class Reference

A rotation followed by a translation.

```
#include <RotTrans2D.h>
```

Collaboration diagram for RotTrans2D:



Public Member Functions

- [RotTrans2D](#) (double ang, double tx, double ty)
- [RotTrans2D](#) (double ang, const [Point2D](#) &t)
- [RotTrans2D](#) (double ang, const [Point2D](#) &fixpt, const [Point2D](#) &t)
- [RotTrans2D](#) ()
- [RotTrans2D inv](#) () const
Generate the inverse operation of this.
- [Point2D apply](#) (const [Point2D](#) &pt) const

Public Attributes

- double [angle](#)
The angle of rotation (radians).
- [Point2D trans](#)
The translation vector.
- double [sc](#) [2]
The sine and cosine of the angle.

5.10.1 Detailed Description

A rotation followed by a translation.

- The class represents an active ccw rotation around (0,0) specified by an angle followed by a translation specified by its 2 delta coordinates.

A rotation around another fixed point followed by a translation is also represented by this class, but mapped on a rotation around (0,0).

Note that the two components of the transformation, the rotation and translation, are not commutative operations in general.

Note also that the translation vector is to be interpreted in the original coordinate system (as indicated by *active*).

Since

2013-07-04

Author

Richard J. Mathar

5.10.2 Constructor & Destructor Documentation

5.10.2.1 [RotTrans2D::RotTrans2D](#) (double *ang*, double *x*, double *y*)

Create a rotation-translation given the angle and translation vector.

Parameters

<i>ang</i>	The angle (ccw, radians)
<i>x</i>	The x coordinate of the translation.

<i>y</i>	The y coordinate of the translation
----------	-------------------------------------

5.10.2.2 RotTrans2D::RotTrans2D (double *ang*, const Point2D & *t*)

Create a rotation-translation given the angle and translation vector.

Parameters

<i>ang</i>	The angle (ccw, radians)
<i>t</i>	The translation vector represented by a point in the original coordinates.

5.10.2.3 RotTrans2D::RotTrans2D (double *ang*, const Point2D & *fixpt*, const Point2D & *t*)

Create a rotation-translation given the angle and translation vector. The initial rotation is specified by an angle and a fixed point of the rotation.

Parameters

<i>ang</i>	The angle (ccw, radians)
<i>fixpt</i>	The fixed point for the rotation.
<i>t</i>	The translation vector represented by a point in the original coordinates.

5.10.2.4 RotTrans2D::RotTrans2D ()

Create a dummy rotation-translation (which is not rotating or translating). This results in a rotation by an angle of zero and translation by a vector of zero length.

5.10.3 Member Function Documentation

5.10.3.1 RotTrans2D RotTrans2D::inv () const

Generate the inverse operation of this.

Returns

The left inverse operation M' , defined by $M' * \text{this} = \text{identity}$, or the right inverse operation M' defined by $\text{this} * M' = \text{identity}$. In the operator products, the latter one (the one to the right of the multiplication symbol) is executed first.

5.10.3.2 Point2D RotTrans2D::apply (const Point2D & *pt*) const

Apply the transformation to a point.

Parameters

<i>pt</i>	The point to be rotated-translated.
-----------	-------------------------------------

Returns

The rotated coordinates.

5.10.4 Member Data Documentation

5.10.4.1 double RotTrans2D::angle

The angle of rotation (radians).

Points are rotated ccw in the 2D plane by this angle.

5.10.4.2 Point2D RotTrans2D::trans

The translation vector.

5.10.4.3 double RotTrans2D::sc[2]

The sine and cosine of the angle.

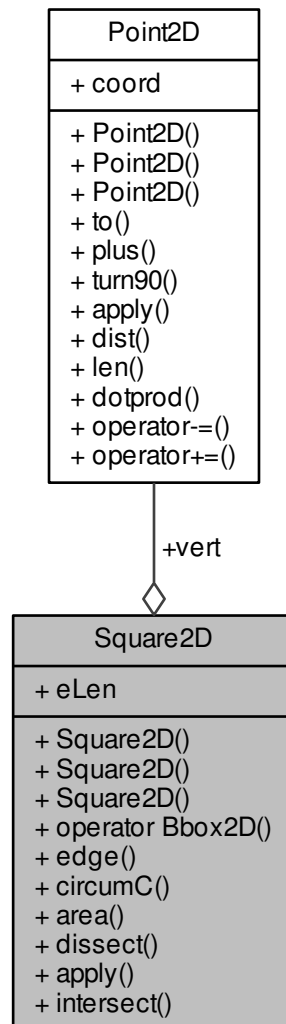
Stored separately to avoid re-computation of these two values if the rotation is applied often.

5.11 Square2D Class Reference

A square represented by the four vertices of the corners.

```
#include <Square2D.h>
```

Collaboration diagram for Square2D:



Public Member Functions

- [Square2D](#) (const [Point2D](#) &pt1, const [Point2D](#) &pt2)
Create a planar square given the first two adjacent vertices.
- [Square2D](#) (const [Point2D](#) &pt1, const [Point2D](#) &pt2, const [Point2D](#) &pt3, const [Point2D](#) &pt4)
Create a planar square given all four vertices.
- [Square2D](#) ()
- [operator Bbox2D](#) () const
Generate the bounding box of this square.
- [Line2D edge](#) (int no) const
- [Circle2D circumC](#) () const
- double [area](#) () const
- [Tria2D * dissect](#) () const
- [Square2D apply](#) (const [RotTrans2D](#) &rt) const
Compute the square that is rotated-translated.
- vector< [Tria2D](#) > [intersect](#) (const [Square2D](#) &oth) const
Compute the common area (intersection) between this and another square.

Public Attributes

- [Point2D vert](#) [4]
The points at the vertices.
- double [eLen](#)
Edge length.

5.11.1 Detailed Description

A square represented by the four vertices of the corners.

Since

2013-07-03

Author

Richard J. Mathar

5.11.2 Constructor & Destructor Documentation

5.11.2.1 [Square2D::Square2D](#) (const [Point2D](#) & pt1, const [Point2D](#) & pt2)

Create a planar square given the first two adjacent vertices.

The third and fourth vertex are defined by orthogonal extension off the baseline between the first and second vertex.

Parameters

<i>pt1</i>	The first vertex.
<i>pt2</i>	The second vertex.

5.11.2.2 [Square2D::Square2D](#) (const [Point2D](#) & pt1, const [Point2D](#) & pt2, const [Point2D](#) & pt3, const [Point2D](#) & pt4)

Create a planar square given all four vertices.

The four vertices are supposed to be given in ccs order. No checking on the length and mutual orthogonality of the edges is done!

Parameters

<i>pt1</i>	The first vertex.
<i>pt2</i>	The second vertex.
<i>pt3</i>	The third vertex.
<i>pt4</i>	The fourth vertex.

5.11.2.3 Square2D::Square2D ()

Create an empty square with four vertices all at the origin.

5.11.3 Member Function Documentation**5.11.3.1 Square2D::operator Bbox2D () const**

Generate the bounding box of this square.

Returns

The quadrangular bounding box.

5.11.3.2 Line2D Square2D::edge (int no) const

Create a line that connects vertex number 'no' with the next vertex along the edge.

Parameters

<i>no</i>	The edge number in the range 0 to 3.
-----------	--------------------------------------

Returns

The line that connects point no with point no+1. Edge 0 connects vertex 0 to 1. Edge 1 connects vertex 1 to 2. Edge 2 connects vertex 2 to 3. Edge 3 connects vertex 3 to 0.

5.11.3.3 Circle2D Square2D::circumC () const

Compute the circumcircle.

Returns

The circumcircle. The perimeter of the circle touches all 4 vertices of the Square.

5.11.3.4 double Square2D::area () const

Compute the area.

Returns

The area. Square of the edge length

5.11.3.5 Tria2D * Square2D::dissect () const

Dissect the square into two triangles along a diagonal.

Returns

The two triangles. The orientation of the triangles is individually the same as the orientation of the square. We also guarantee that the first two edges of each triangle are orthogonal, which implies that the circumcircles of these are centered at the (common) longest edge.

5.11.3.6 Square2D Square2D::apply (const RotTrans2D & rt) const

Compute the square that is rotated-translated.

Parameters

<i>in</i>	<i>rt</i>	The rotation-translation to be applied
-----------	-----------	--

Returns

The square defined by individual rotation of all 4 vertices of this.

5.11.3.7 vector< Tria2D > Square2D::intersect (const Square2D & *oth*) const

Compute the common area (intersection) between this and another square.

Returns

The vector of mutually non-intersecting pieces of the common area of both polygons. If there is no overlap, the vector that is returned is empty.

5.11.4 Member Data Documentation**5.11.4.1 Point2D Square2D::vert[4]**

The points at the vertices.

5.11.4.2 double Square2D::eLen

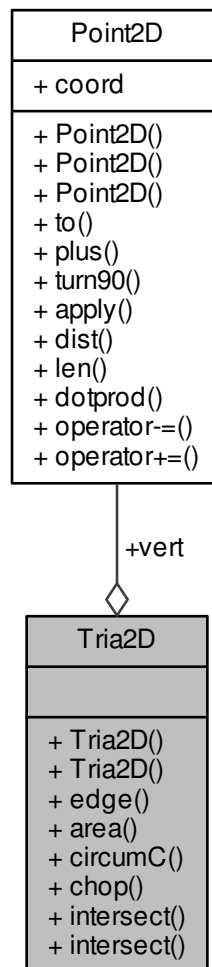
Edge length.

5.12 Tria2D Class Reference

A triangle represented by the Cartesian coordinates of its three vertices.

```
#include <Tria2D.h>
```


Collaboration diagram for Tria2D:



Public Member Functions

- [Tria2D](#) (const [Point2D](#) &pt1, const [Point2D](#) &pt2, const [Point2D](#) &pt3)
- [Tria2D](#) ()
- [Line2D](#) [edge](#) (int no) const
- double [area](#) () const
- [Circle2D](#) [circumC](#) () const
- vector< [Tria2D](#) > [chop](#) (const [Line2D](#) &lin) const
- vector< [Tria2D](#) > [intersect](#) (const [Tria2D](#) &oth) const
Compute the common portion (intersection) between this and another triangle.
- vector< [Tria2D](#) > [intersect](#) (const [Square2D](#) &oth) const
Compute the common area (intersection) between this and a square.

Public Attributes

- [Point2D](#) [vert](#) [3]

The three points at the vertices.

5.12.1 Detailed Description

A triangle represented by the Cartesian coordinates of its three vertices.

Since

2013-07-03

Author

Richard J. Mathar

5.12.2 Constructor & Destructor Documentation

5.12.2.1 `Tria2D::Tria2D (const Point2D & pt1, const Point2D & pt2, const Point2D & pt3)`

Create a planar triangle given its three vertices.

Parameters

<i>pt1</i>	The first vertex.
<i>pt2</i>	The second vertex.
<i>pt3</i>	The third vertex.

5.12.2.2 `Tria2D::Tria2D ()`

Create an empty triangle with three vertices all at the origin.

5.12.3 Member Function Documentation

5.12.3.1 `Line2D Tria2D::edge (int no) const`

Create a line that connects vertex number 'no' with the next vertex along the edge.

Parameters

<i>no</i>	The edge number in the range 0 to 2.
-----------	--------------------------------------

Returns

The line that connects point no with point no+1. Edge 0 connects vertex 0 to 1. Edge 1 connects vertex 1 to 2. Edge 2 connects vertex 2 to 0.

5.12.3.2 `double Tria2D::area () const`

Compute the area of the triangle.

Returns

The area of all points within the triangle.

5.12.3.3 `Circle2D Tria2D::circumC () const`

Compute the circumcircle.

Returns

The circumcircle. By definition, the perimeter of the circle touches all three vertices of the triangle.

5.12.3.4 `vector< Tria2D > Tria2D::chop (const Line2D & lin) const`

Compute the portion of this that is left from the infinite line `lin`.

Parameters

<i>lin</i>	The line that cuts the 2D plane in half.
------------	--

Returns

The vector of mutually non-intersecting pieces of the subarea of this that is to the left from the line.

5.12.3.5 vector< Tria2D > Tria2D::intersect (const Tria2D & oth) const

Compute the common portion (intersection) between this and another triangle.

Returns

The vector of mutually non-intersecting pieces of the common area of both triangles. If they do not overlap, the vector is empty.

5.12.3.6 vector< Tria2D > Tria2D::intersect (const Square2D & oth) const

Compute the common area (intersection) between this and a square.

Returns

The vector of mutually non-intersecting pieces of the common area of both polygons.. If they do not overlap, the vector is empty.

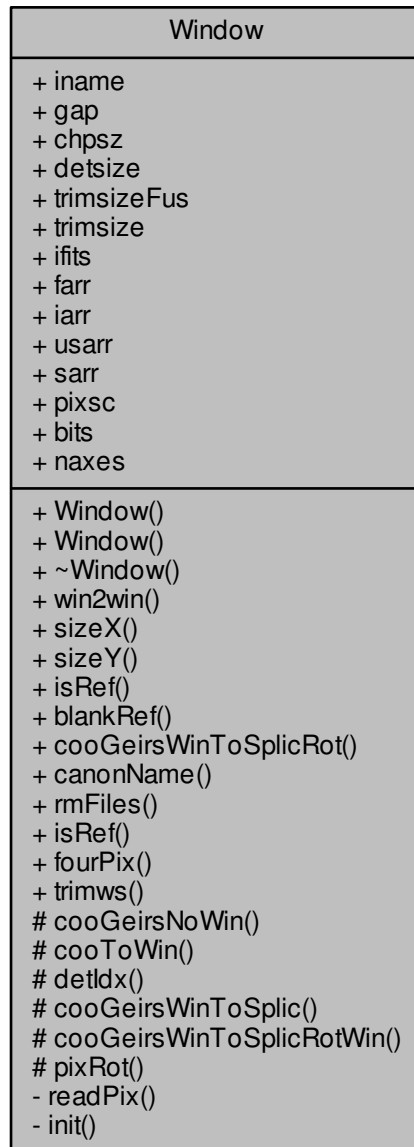
5.12.4 Member Data Documentation**5.12.4.1 Point2D Tria2D::vert[3]**

The three points at the vertices.

5.13 Window Class Reference

```
#include <Window.h>
```

Collaboration diagram for Window:



Public Member Functions

- [Window](#) (char *fitsInname, int gp=0, int csiz=2048)
- [Window](#) (string fitsInname, int gp=0, int csiz=2048)
- [~Window](#) ()
Destructor.
- void [win2win](#) (const int rotRight90, const bool flip)
Compute the window location after splicing and optional flip-rotation.
- int [sizeX](#) () const
The width along x in pixel units.

- int `sizeY` () const
The width along y in pixel units.
- bool `isRef` (int xin, int yin) const
Decide whether a pixel is one of the reference pixel in one of the 4 frame borders.
- void `blankRef` (int blank)
Fill any pixel in one of the four pixel borders (within the 4pixel limit) by the blank.
- void `cooGeirsWinToSplicRot` (int coo[2], const int rotRight90, const bool flip)
Convert the coordinate from fused (zero-gap) windowed to global mosaic coordinate (spliced) system.
- string `canonicalName` ()
Generate a <INSTRU>.YYYY-MM-DDTHH-MM-SS.sss.fits string name.
- void `rmFiles` (bool verbose=false)
Delete the file that contains the data used on construction.

Static Public Member Functions

- static bool `isRef` (int xin, int yin, int xchipsize, int ychipsize)
Decide whether a pixel is one of the reference pixel in one of the 4 frame borders.
- static void `fourPix` (const string &tsiz, int coo[4], bool relwidth)
Extract the [xl:xh,yl:yh] four parameters from the bracket.
- static string `trimws` (const string &instring)
Strip leading and trailing white space from a string.

Public Attributes

- string `iname`
Name of the input file.
- int `gap`
Gap (measured in pixels) between the chips of the mosaic.
- int `chpsz`
Size (measured in pixels) of the single chip of the mosaic.
- int `detsize` [4]
Size (measured in pixels) of the fused array of chips.
- int `trimsizFus` [4]
Window origin and extension in the coordinate system of the fused (gapless) mosaic.
- int `trimsiz` [4]
Window origin and extension in the coordinate system of the spliced mosaic.
- FITS * `ifits`
The FITS file that will be read/scanned.
- valarray< float > `farr`
array of pixels in floating point units.
- valarray< int > `iarr`
Array of pixels in 32bit integer units.
- valarray< unsigned short > `usarr`
Array of pixels in 16bit integer units.
- valarray< unsigned short > `sarr`
Array of pixels in 16bit integer units.
- float `pixsc`
Pixel scale in units of degrees on the sky.
- long `bits`
The indication of image type (integer, short, float...)
- long `naxes`
The indication of dimension of the image (2=flat, 3=cubes,...)

Protected Member Functions

- void `cooGeirsNoWin` (int coo[2])
Convert the coordinate in the fused (zero-gap) windowed coordinate system to non-windowed.
- void `cooToWin` (int coo[2])
Convert the coordinate in non-windowed coordinate system to windowed.
- void `detIdx` (const int coo[2], int idx[2])
Compute the chip number in the fused (zero-gap) global mosaic coordinate system.
- void `cooGeirsWinToSplic` (int coo[2])
Convert the coordinate from fused (zero-gap) windowed to global mosaic coordinate (spliced) system.
- void `cooGeirsWinToSplicRotWin` (int coo[2], const int rotRight90, const bool flip)
Convert the coordinate from fused (zero-gap) windowed to mosaic windowed/rotated coordinate (spliced) system.

Static Protected Member Functions

- static void `pixRot` (int coo[2], int rotRight90, bool flip)
Map a pixel in the input rectangular array to a pixel in the output array.

Private Member Functions

- void `readPix` (bool verbose)
Read the pixel data of the primary data unit (image).
- void `init` (bool verbose)
Scan the bare primary information in the FITS header.

5.13.1 Detailed Description

Since

2012-11-08

Author

Richard J. Mathar

5.13.2 Constructor & Destructor Documentation

5.13.2.1 Window::Window (char * fitsName, int gp = 0, int csiz = 2048)

Parameters

in	<i>fitsName</i>	The name of the FITS file to be read.
in	<i>gp</i>	The width of the gap between individual chips in the mosaic in units of pixels.
in	<i>csiz</i>	The dimension along each edge of each chip in pixels.

Since

2012-10-23

Author

Richard J. Mathar

5.13.2.2 Window::Window (string fitsName, int gp = 0, int csiz = 2048)

Parameters

in	<i>fitsname</i>	The name of the FITS file to be read.
in	<i>gp</i>	The width of the gap between individual chips in the mosaic in units of pixels.
in	<i>csiz</i>	The dimension along each edge of each chip in pixels.

Since

2012-10-23

Author

Richard J. Mathar

5.13.2.3 Window::~Window ()

Destructor.

5.13.3 Member Function Documentation**5.13.3.1 void Window::win2win (const int *rotRight90*, const bool *flip*)**

Compute the window location after splicing and optional flip-rotation.

Parameters

in	<i>rotRight90</i>	Number of right-90 rotations requested.
in	<i>flip</i>	If true, perform another right-left flip around the y-coordinate.

5.13.3.2 int Window::sizeX () const

The width along x in pixel units.

Returns

The horizontal size of the window in pixels. This refers to the original orientation, not the optionally rotated or flipped one.

Since

2012-11-07

5.13.3.3 int Window::sizeY () const

The width along y in pixel units.

Returns

The vertical size of the window in pixels. This refers to the original orientation, not the optionally rotated or flipped one.

Since

2012-11-07

5.13.3.4 bool Window::isRef (int *xin*, int *yin*, int *xchipsize*, int *ychipsize*) [static]

Decide whether a pixel is one of the reference pixel in one of the 4 frame borders.

This supports elimination of the reference pixels on Hawaii2 detectors.

Parameters

<code>in</code>	<code>xin</code>	The x coordinate in the range 0 to <code>xchipsize-1</code> (inclusive) Independent of windowing, this coordinates refers to <code>x=0</code> as the lower left edge coordinate of the entire mosaic.
<code>in</code>	<code>yin</code>	The y coordinate in the range 0 to <code>ychipsize-1</code> (inclusive) Independent of windowing, this coordinates refers to <code>y=0</code> as the lower left edge coordinate the entire mosaic.
<code>in</code>	<code>xchipsize</code>	The number of pixels along x.
<code>in</code>	<code>ychipsize</code>	The number of pixels along y.

Returns

true if `(xin,yin)` lie in one of the 4-pixel white frames around the full frame.

5.13.3.5 `bool Window::isRef (int xin, int yin) const`

Decide whether a pixel is one of the reference pixel in one of the 4 frame borders.

This supports elimination of the reference pixels on Hawaii2 detectors.

Parameters

<code>in</code>	<code>xin</code>	The x coordinate in the range 0 to <code>xchipsize-1</code> (inclusive) Independent of windowing, this coordinates refers to <code>x=0</code> as the lower left edge coordinate of the entire mosaic.
<code>in</code>	<code>yin</code>	The y coordinate in the range 0 to <code>ychipsize-1</code> (inclusive) Independent of windowing, this coordinates refers to <code>y=0</code> as the lower left edge coordinate the entire mosaic.

Returns

true if `(xin,yin)` lie in one of the 4-pixel white frames around the full frame.

5.13.3.6 `void Window::blankRef (int blank)`

Fill any pixel in one of the four pixel borders (within the 4pixel limit) by the blank.

This supports elimination of the reference pixels on Hawaii2 detectors.

Parameters

<code>in</code>	<code>blank</code>	The value to replace all reference values.
-----------------	--------------------	--

Since

2012-11-19

5.13.3.7 `void Window::cooGeirsWinToSplicRot (int coo[2], const int rotRight90, const bool flip)`

Convert the coordinate from fused (zero-gap) windowed to global mosaic coordinate (spliced) system.

Parameters

<code>in, out</code>	<code>coo</code>	
----------------------	------------------	--

Since

2012-11-07

5.13.3.8 `void Window::fourPix (const string & tsiz, int coo[4], bool relwidths) [static]`

Extract the `[xl:xh,yl:yh]` four parameters from the bracket.

Parameters

<i>in</i>	<i>tsiz</i>	with four integer values, colon and comma-separated. The interpretation for <code>relwidths=true</code> is that the value of ranges in x is from <code>xl</code> (inclusive) to <code>xl+xh</code> (exclusive) and in y from <code>yl</code> (inclusive) to <code>yl+yh</code> (exclusive). The interpretation for <code>relwidths=false</code> is that the value of ranges in x is from <code>xl</code> (inclusive) to <code>xh</code> (exclusive) and in y from <code>yl</code> (inclusive) to <code>yh</code> (exclusive).
<i>out</i>	<i>coo</i>	The four coordinates <code>xl</code> , <code>xh</code> , <code>yl</code> , <code>yh</code> . If the format of the string does not provide the two brackets, two colons and comma, the values are not changed.
<i>in</i>	<i>relwidths</i>	If true, the 2nd pair of coordinates is interpreted as relative sizes (widths). If false, the pair is in the same absolute coordinate system as the first pair.

Since

2012-11-06

5.13.3.9 string Window::canonicalName ()

Generate a `<INSTRU>.YYYY-MM-DDTHH-MM-SS.sss.fits` string name.

Since

2012-11-20

Author

Richard J. Mathar

5.13.3.10 string Window::trimws (const string & *instring*) [static]

Strip leading and trailing white space from a string.

Parameters

<i>in</i>	<i>instring</i>	The initial string from which nonprintable leading and trailing characters or white space (tabs, blanks) ought to be removed.
-----------	-----------------	---

Returns

The string with leading and trailing blanks, tabs etc removed.

5.13.3.11 void Window::rmFiles (bool *verbose* = false)

Delete the file that contains the data used on construction.

Obviously, this is a risky operation and may lead to loss of data.

Parameters

<i>in</i>	<i>verbose</i>	If true, print names of files deleted to stdout.
-----------	----------------	--

Since

2012-11-20

Author

Richard J. Mathar

5.13.3.12 void Window::cooGeirsNoWin (int *coo*[2]) [inline], [protected]

Convert the coordinate in the fused (zero-gap) windowed coordinate system to non-windowed.

Parameters

<i>in, out</i>	<i>coo</i>	On input, the x and y coordinate in the window and fused coordinate system. On output, the x and y coordinate in the window and fused coordinate system.
----------------	------------	---

5.13.3.13 void Window::cooToWin (int *coo*[2]) [inline],[protected]

Convert the coordinate in non-windowed coordinate system to windowed.

Parameters

<i>in, out</i>	<i>coo</i>	On input, the x and y coordinate in the windowed spliced coordinate system. On output, the x and y coordinate in the global spliced coordinate system.
----------------	------------	---

5.13.3.14 void Window::detIdx (const int *coo*[2], int *idx*[2]) [inline],[protected]

Compute the chip number in the fused (zero-gap) global mosaic coordinate system.

Parameters

<i>in</i>	<i>coo</i>	
<i>out</i>	<i>idx</i>	

Since

2012-11-07

5.13.3.15 void Window::pixRot (int *coo*[2], int *rotRight90*, bool *flip*) [static],[protected]

Map a pixel in the input rectangular array to a pixel in the output array.

Parameters

<i>in, out</i>	<i>coo</i>	[0] the x and [1] the y coordinate before and after the rotation. On output, the two coordinates may have picked up any of the 4 sign combinations. So this is a pure rotation on the Gaussian integer coordinate system. No shift is involved to translate the coordinates back to some sort of first quadrant.
<i>in</i>	<i>rotRight90</i>	Count of right rotations in units of 90 degrees. This value is used modulo 4, so effectively between 1 and 3. 0 has no effect, unless combined with the flip.
<i>in</i>	<i>flip</i>	Request a flip around the y-axis. This equals sign toggling of x-coordinates after any rotation.

5.13.3.16 void Window::cooGeirsWinToSplic (int *coo*[2]) [protected]

Convert the coordinate from fused (zero-gap) windowed to global mosaic coordinate (spliced) system.

Parameters

<i>in, out</i>	<i>coo</i>	
----------------	------------	--

Since

2012-11-07

5.13.3.17 void Window::cooGeirsWinToSplicRotWin (int *coo*[2], const int *rotRight90*, const bool *flip*) [protected]

Convert the coordinate from fused (zero-gap) windowed to mosaic windowed/rotated coordinate (spliced) system.

Parameters

<i>in, out</i>	<i>COO</i>
----------------	------------

Since

2012-11-07

5.13.3.18 void Window::readPix (bool *verbose*) [private]

Read the pixel data of the primary data unit (image).

Parameters

<i>in</i>	<i>verbose</i>	If true, write some output to stdout.
-----------	----------------	---------------------------------------

Since

2012-10-18

Author

Richard J. Mathar

5.13.3.19 void Window::init (bool *verbose*) [private]

Scan the bare primary information in the FITS header.

Read INSTRUME to have some input on the mosaic size. Read DETSIZE which is the preferred way to have some input on the mosaic size. Read SAVEAREA (GEIRS specific, deprecated) and TRIMSIZE to determine the window location

Author

Richard J. Mathar

5.13.4 Member Data Documentation**5.13.4.1 string Window::iname**

Name of the input file.

The principal use is to look into the primary header for the SAVEAREA (TRIMSIZE) keyword that relocates this window in the coordinate system of the mosaic of fused chips.

5.13.4.2 int Window::gap

Gap (measured in pixels) between the chips of the mosaic.

This is considered the same horizontally and vertically.

5.13.4.3 int Window::chpsz

Size (measured in pixels) of the single chip of the mosaic.

This is only considering quadratic chips (same x and y extent)

5.13.4.4 int Window::detsize[4]

Size (measured in pixels) of the fused array of chips.

This is the product of chip count and chpsz in the horizontal and vertical directions. The interpretation is that the xrange is from [0] to [1] (exclusive), the y range from [2] to [3] (exclusive) and [0]=[2]=0 with the usual 0-based C/C++/Java convention.

5.13.4.5 int Window::trimsizeFus[4]

Window origin and extension in the coordinate system of the fused (gapless) mosaic.

The four components of the array are following the same convention as detsize.

5.13.4.6 int Window::trimsize[4]

Window origin and extension in the coordinate system of the spliced mosaic.

The four components of the array are following the same convention as detsize. If some subareas of the window are located in any but the lower-left chip, the components will differ (and be larger than) the associated components in trimsizeFus.

5.13.4.7 FITS* Window::ifits

The FITS file that will be read/scanned.

5.13.4.8 valarray<float> Window::farr

array of pixels in floating point units.

Empty if this is not a floating point type.

5.13.4.9 valarray<int> Window::iarr

Array of pixels in 32bit integer units.

Empty if this is not a integer type.

5.13.4.10 valarray<unsigned short> Window::usarr

Array of pixels in 16bit integer units.

Empty if this is not a unsigned short integer type.

5.13.4.11 valarray<unsigned short> Window::sarr

Array of pixels in 16bit integer units.

Empty if this is not a short integer type.

5.13.4.12 float Window::pixsc

Pixel scale in units of degrees on the sky.

To be used to convert pixels to WCS coordinates.

5.13.4.13 long Window::bits

The indication of image type (integer, short, float...)

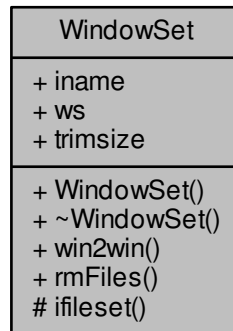
5.13.4.14 long Window::naxes

The indication of dimension of the image (2=flat, 3=cubes,...)

5.14 WindowSet Class Reference

```
#include <WindowSet.h>
```

Collaboration diagram for WindowSet:



Public Member Functions

- [WindowSet](#) (const char *fitsInname, int gp=0, int csiz=2048)
- [~WindowSet](#) ()
Destructor.
- void [win2win](#) (const int rotRight90, const bool flip)
Compute the window location after splicing and optional flip-rotation.
- void [rmFiles](#) (bool verbose=false)
Remove the input files from the file system.

Public Attributes

- string [iname](#)
Name of the input file.
- vector< [Window](#) * > [ws](#)
The individual windows.
- int [trimsize](#) [4]
[Window](#) superframe origin and extension in the coordinate system of the spliced mosaic.

Static Protected Member Functions

- static vector< string > [ifileset](#) (const char *fitsInname)
Determine the list of all fits file names that match the base name.

5.14.1 Detailed Description

Since

2012-11-08

Author

Richard J. Mathar

5.14.2 Constructor & Destructor Documentation

5.14.2.1 WindowSet::WindowSet (const char * *fitsname*, int *gp* = 0, int *csiz* = 2048)

Parameters

in	<i>fitsname</i>	The name of the FITS file to be read.
in	<i>gp</i>	The width of the gap between individual chips in the mosaic in units of pixels.
in	<i>csiz</i>	The dimension along each edge of each chip in pixels.

Since

2012-10-23

Author

Richard J. Mathar

5.14.2.2 WindowSet::~~WindowSet ()

Destructor.

5.14.3 Member Function Documentation

5.14.3.1 void WindowSet::win2win (const int *rotRight90*, const bool *flip*)

Compute the window location after splicing and optional flip-rotation.

Parameters

in	<i>rotRight90</i>	Number of right-90 rotations requested.
in	<i>flip</i>	If true, perform antoher right-left flip around the y-coordinate.

5.14.3.2 void WindowSet::rmFiles (bool *verbose* = false)

Remove the input files from the file system.

This hazardous action removes the FITS files that have been used to define the windows and their contents.

Parameters

in	<i>verbose</i>	If true, print each file's name removed to stdout.
----	----------------	--

Since

2012-11-20

Author

Richard J. Mathar

5.14.3.3 vector< string > WindowSet::ifileset (const char * *fitsname*) [static],[protected]

Determine the list of all fits file names that match the base name.

Parameters

<i>in</i>	<i>fitsname</i>	The basename name of the FITS file to be read.
-----------	-----------------	--

Returns

The existing files of the format of the argument with suffix `.fits`, and the existing files with suffices `*_wini.fits`, with `i` a set of consecutive increasing integer numbers.

5.14.4 Member Data Documentation**5.14.4.1 string WindowSet::iname**

Name of the input file.

The principal use is to look into the primary header for the SAVEARE (TRIMSIZE) keyword that relocates this window in the coordinate system of the mosaic of fused chips.

5.14.4.2 vector<Window *> WindowSet::ws

The individual windows.

At this point an ugly decision is made to collect the vector of pointers to windows, because the `Window` class contains a pointer to FITS for which no copy ctor exists, so no copy ctor for `Window` exists (and that would be needed to avoid that at the time the dtor of `ws[]` goes out of scope the FITS contents is deleted, although we'd like to have access to the keywords later on...)

5.14.4.3 int WindowSet::trimsize[4]

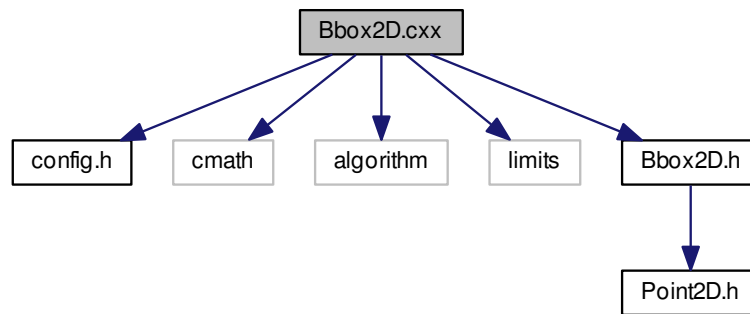
`Window` superframe origin and extension in the coordinate system of the spliced mosaic.

This information is only relevant if one unites all windows in the output, but not if the subareas are individually spread over extension headers.

6 File Documentation**6.1 Bbox2D.cxx File Reference**

```
#include "config.h"
#include <cmath>
#include <algorithm>
#include <limits>
#include "Bbox2D.h"
```

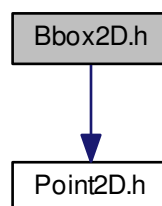

Include dependency graph for Bbox2D.cxx:



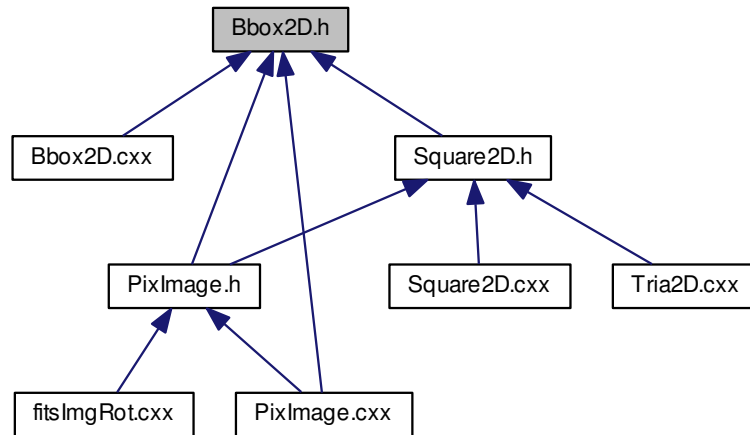
6.2 Bbox2D.h File Reference

```
#include "Point2D.h"
```

Include dependency graph for Bbox2D.h:



This graph shows which files directly or indirectly include this file:



Classes

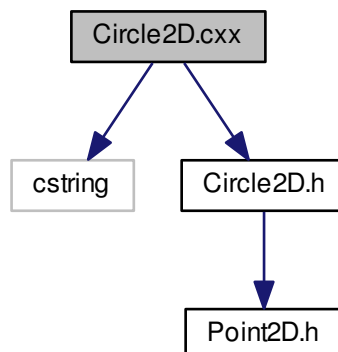
- class [Bbox2D](#)

A 2-dimensional rectangular boundary box parallel to the two Cartesian axes.

6.3 Circle2D.cxx File Reference

```
#include <cstring>
#include "Circle2D.h"
```

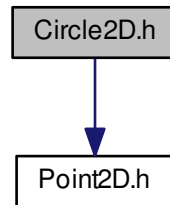
Include dependency graph for `Circle2D.cxx`:



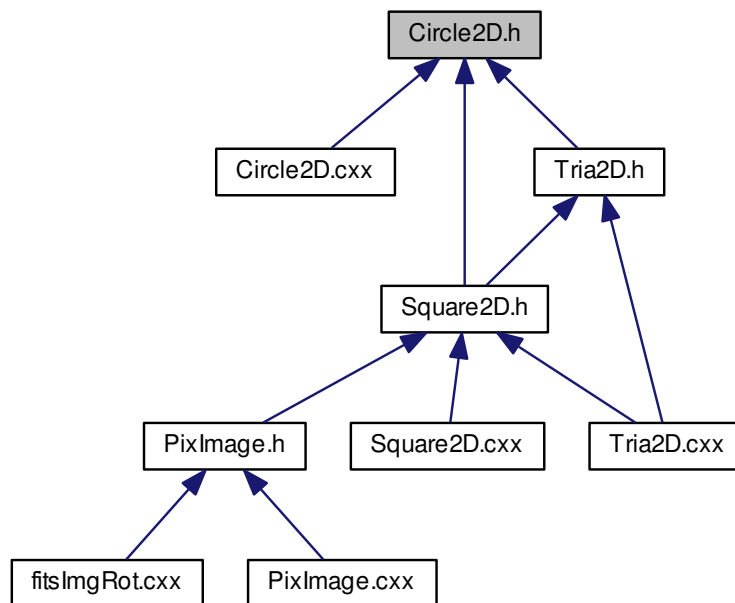
6.4 Circle2D.h File Reference

```
#include "Point2D.h"
```

Include dependency graph for Circle2D.h:



This graph shows which files directly or indirectly include this file:



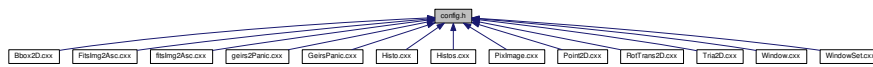
Classes

- class [Circle2D](#)

A circle represented by center point coordinate and radius.

6.5 config.h File Reference

This graph shows which files directly or indirectly include this file:



Macros

- #define [HAVE_CMATH](#)
- #define [HAVE_CSTRING](#)
- #define [HAVE_INTTYPES_H](#)
- #define [HAVE_LIBCCFITS](#)
- #define [HAVE_LIBM](#)
- #define [HAVE_MATH_H](#)
- #define [HAVE_MEMCPY](#)
- #define [HAVE_MEMORY_H](#)
- #define [HAVE_SINCOS](#)
- #define [HAVE_STDINT_H](#)
- #define [HAVE_STDLIB_H](#)
- #define [HAVE_STRINGS_H](#)
- #define [HAVE_STRING_H](#)
- #define [HAVE_SYS_STAT_H](#)
- #define [HAVE_SYS_TYPES_H](#)
- #define [HAVE_UNISTD_H](#)
- #define [PACKAGE_BUGREPORT](#)
- #define [PACKAGE_NAME](#)
- #define [PACKAGE_STRING](#)
- #define [PACKAGE_TARNAME](#)
- #define [PACKAGE_URL](#)
- #define [PACKAGE_VERSION](#)
- #define [STDC_HEADERS](#)

6.5.1 Macro Definition Documentation

6.5.1.1 #define HAVE_CMATH

6.5.1.2 #define HAVE_CSTRING

6.5.1.3 #define HAVE_INTTYPES_H

6.5.1.4 #define HAVE_LIBCCFITS

6.5.1.5 #define HAVE_LIBM

6.5.1.6 #define HAVE_MATH_H

6.5.1.7 #define HAVE_MEMCPY

6.5.1.8 #define HAVE_MEMORY_H

6.5.1.9 #define HAVE_SINCOS

6.5.1.10 #define HAVE_STDINT_H

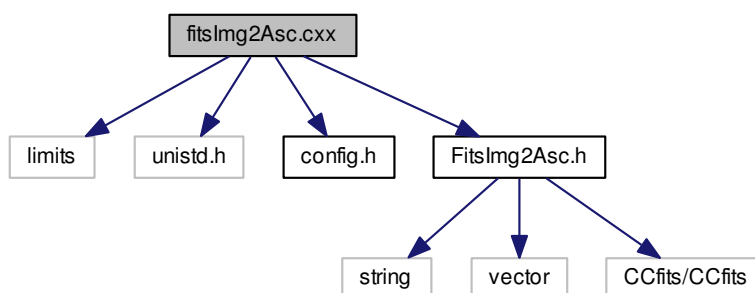
- 6.5.1.11 `#define HAVE_STDLIB_H`
- 6.5.1.12 `#define HAVE_STRINGS_H`
- 6.5.1.13 `#define HAVE_STRING_H`
- 6.5.1.14 `#define HAVE_SYS_STAT_H`
- 6.5.1.15 `#define HAVE_SYS_TYPES_H`
- 6.5.1.16 `#define HAVE_UNISTD_H`
- 6.5.1.17 `#define PACKAGE_BUGREPORT`
- 6.5.1.18 `#define PACKAGE_NAME`
- 6.5.1.19 `#define PACKAGE_STRING`
- 6.5.1.20 `#define PACKAGE_TARNAME`
- 6.5.1.21 `#define PACKAGE_URL`
- 6.5.1.22 `#define PACKAGE_VERSION`
- 6.5.1.23 `#define STDC_HEADERS`

6.6 fitsImg2Asc.cxx File Reference

The program fitsImg2Asc converts the image in the primary HDU of a FITS file to an ASCII format.

```
#include <limits>
#include <unistd.h>
#include "config.h"
#include "FitsImg2Asc.h"
```

Include dependency graph for fitsImg2Asc.cxx:



Functions

- void `usage` (char *argv0)
Print a usage syntax message detailing the command line.
- int `main` (int argc, char *argv[])
The program fitsImg2Asc converts the image in the primary HDU of a FITS file to an ASCII format.

6.6.1 Detailed Description

The program `fitsImg2Asc` converts the image in the primary HDU of a FITS file to an ASCII format.

6.6.2 Function Documentation

6.6.2.1 void usage (char * argv0)

Print a usage syntax message detailing the command line.

Parameters

<code>in</code>	<code>argv0</code>	The name of the main program.
-----------------	--------------------	-------------------------------

Since

2012-10-18

6.6.2.2 int main (int argc, char * argv[])

The program `fitsImg2Asc` converts the image in the primary HDU of a FITS file to an ASCII format.

The input file is an image in the FITS file, of which only the first slice is taken if this is a FITS cube.

- 3D view The standard syntax is

```
fitsImg2Asc fitsIn.fits > fitsout.plt
```

or

```
fitsImg2Asc -r '[xstrt:xend,ystrt:yend]' fitsIn.fits > fitsout.plt
```

which means that the command line argument is the name of the FITS file with the image, and the output is redirected into some other file. This output file will be roughly a factor of 4 larger than the input file, and the program will run slower than some people would expect. In almost all cases the field will be too crowded to get useful response times from gnuplot while rotating the image, so the option `-r` allows to take only a rectangular subarea of the image, where the 4 arguments are 0-based ranges for the two pixel axes.

The output contains lines with three values, which is the x coordinate of the pixel, the y coordinate of the pixel, and the value in the image at this pixel.

This ASCII file has been targeted for use with a gnuplot(1) session e.g. like: `gnuplot gnuplot> set xlabel "x pixel" gnuplot> set ylabel "y pixel" gnuplot> set zlabel "adu" gnuplot> splot "..." wi li # insert the fitsout.plt file data name here gnuplot> set grid gnuplot> set contour base gnuplot> replot gnuplot> set logscale z gnuplot> replot`

Example: `fitsImg2Asc -r '[200:800,1200:1800]' fitsIn.fits > fitsout.plt`

- Histogram The syntax to generate a gnuplot X11 window or EPS file with a histogram of pixel ADU values is triggered by the `-h` option as follows:

```
fitsImg2Asc -h [-l] [-N bins] [-m min] [-M max] [-a [xmin:xmax,ymin-ymax]] [-o fitsout.eps] fitsIn.fits [fitsIn.fits ... ]
```

The option `-N` followed by a positive integer number can be used to specify the number of bins to be generated. If not provided, the program uses a default.

The option `-m` followed by a number is the minimum number on the horizontal axis which delimits the range of ADU's to be shown.

The option `-M` followed by a number is the maximum number on the horizontal axis which delimits the range of ADU's to be shown.

The option `-l` means a logarithmic scale is used on the vertical axis.

The option `-a` followed by four positive integer numbers in brackets selects a quadrangular region (of FITS coordinates) in the image to be scanned. The default is to scan all pixels in the image.

The option -o followed by a file name causes the plot to be moved to a EPS file, not to the screen.

The option -t followed by a file name causes the histogram to be dumped into the named ASCII file.

The other command line arguments are existing fits files which will be read. The gnuplot display shows the count of pixels on a per-file basis which fall into a range of ADU's. There are two variants of showing the result, one with a logarithmic scale for the counts in the bins, one with a linear scale.

Example (which uses the shell's expansion mechanism of file names):

```
fitsImg2Asc -h -m 0 -M 200 aa000[1-8].fits fitsImg2Asc -h -m '-50' -M 50 -N 100 -a '[5:2044,5:2044]' aa000[1-8].fits
```

Example (which shows the selection mechanism of moving to a named extension HDU to locate the image):

```
fitsImg2Asc -h -m '-50' -M 50 -N 100 -a '[5:2044,5:2044]' aa0001.fits'[WIN1]'
```

- Bad pixel mask The syntax to generate a bad pixel mask is:

```
fitsImg2Asc -b [-a '[xstrt:xend,ystrt:yend]'] [-t textout] [-X] [-Y] -m minADU -M maxADU fitsIn.fits fitsOut.fits
```

The mask is defined by investigating the 2D image provided in the input file fitsIn.fits and writing the bad pixel mask to fitsOut.fits.

The option -a defines a subwindow of pixel ranges to be scanned for out-of-range values. The pixels inside the original window but outside that internal window are a frame which is also regarded of containing only bad pixels. So usually for a single Hawaii-2 RG image one would declare the 4-pixel frame to be bad with -a '[5:2044,5:2044]' .

The option -t followed by the name of a file lets the program generate that file where the bad pixels are listed (one by a line) with their 1-based integer x and y coordinates. (This is also the convention of the fixpix routine of the IRAF reduction. It does not produce the generalized format with four parameters equivalent to xstrt, xend, ystrt, yend to define bad pixel blocks.)

The option -X and similarly the option -Y trigger that the bad pixel mask is generated after flipping the image of fitsIn.fits left-right along x or up-down along y. This helps to generate the mask for images that had another WCS orientation convention than the images the bad pixel mask will be generated for.

The option -m (quasi mandatory) defines the minimum ADU value and the option -M (quasi mandatory) defines the maximum ADU value of pixels in fitsIn.fits supposed to be good.

The option -i causes the bad pixel mask to be written with values of 0 for good pixels and values of 1 for bad pixels (as in some IRAF conventions). The default (without the option) is to write 1's for good values and NaN for bad values, so it could be used for multiplicative application for generic pictures.

The two final arguments are the file names of the input image and of the bad pixel image to be created.

Parameters

in	<i>argc</i>	The number of command line switches and arguments.
in	<i>argv</i>	The vector of all command line arguments.

Since

2012-11-25

2013-11-11 Support histograms of images in extension headers

2013-12-04 Implemented bad pixel mask creation

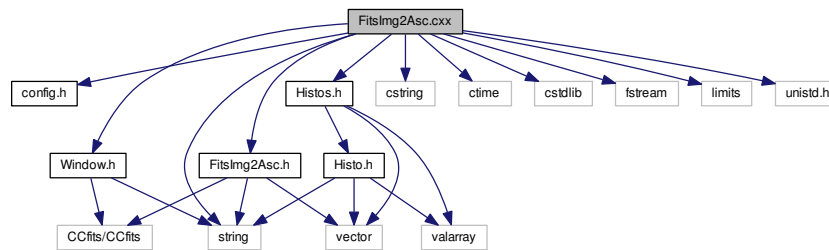
See Also

also <http://heasarc.gsfc.nasa.gov/ftools/caldb/help/ftstat.html>

6.7 FitsImg2Asc.cxx File Reference

```
#include "config.h"
#include <string>
#include <cstring>
#include <ctime>
#include <cstdlib>
#include <fstream>
#include <limits>
#include <unistd.h>
#include "FitsImg2Asc.h"
#include "Window.h"
#include "Histos.h"
```

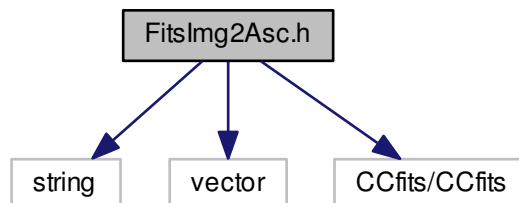
Include dependency graph for FitsImg2Asc.cxx:



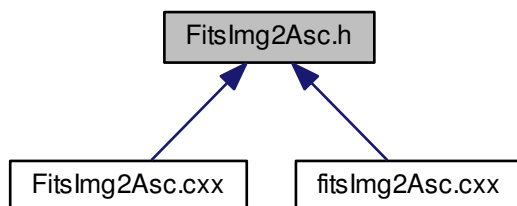
6.8 FitsImg2Asc.h File Reference

```
#include <string>
#include <vector>
#include <CCfits/CCfits>
```

Include dependency graph for FitsImg2Asc.h:



This graph shows which files directly or indirectly include this file:



Classes

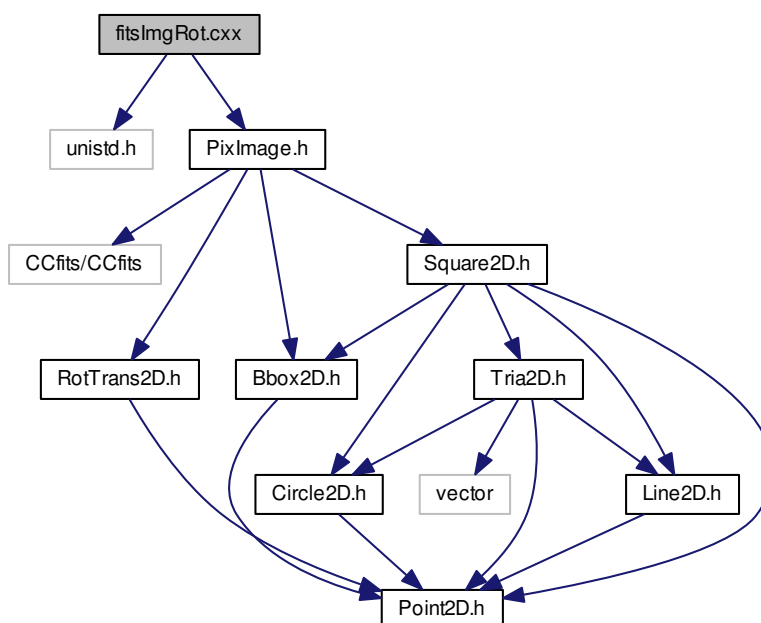
- class [FitsImg2Asc](#)

6.9 fitsImgRot.cxx File Reference

`fitsImgRot` is a C++ program which rotates a FITS image by a variable angle about a variable point.

```
#include <unistd.h>
#include "PixImage.h"
```

Include dependency graph for `fitsImgRot.cxx`:



Functions

- void `usage` (char *argv0)

Print a usage syntax message detailing the command line.

6.9.1 Detailed Description

fitsImgRot is a C++ program which rotates a FITS image by a variable angle about a variable point.

6.9.2 Function Documentation

6.9.2.1 void usage (char * argv0)

Print a usage syntax message detailing the command line.

Parameters

<code>in</code>	<code>argv0</code>	The name of the main program.
-----------------	--------------------	-------------------------------

Since

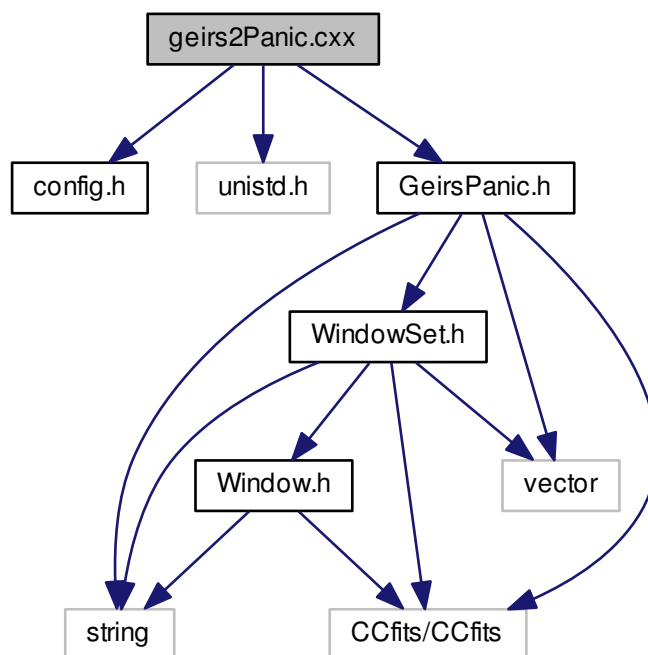
2012-10-18

6.10 geirs2Panic.cxx File Reference

The program geirs2Panic is a postprocessor for FITS mosaic files that have been generated by GEIRS.

```
#include "config.h"
#include <unistd.h>
#include "GeirsPanic.h"
```

Include dependency graph for geirs2Panic.cxx:



Functions

- void [usage](#) (char *argv0, int gap, int chpsz, double north)
Print a usage syntax message detailing the command line.
- int [main](#) (int argc, char *argv[])
The program is a postprocessor for FITS files of CAHA/PANIC that have been generated by GEIRS.

6.10.1 Detailed Description

The program geirs2Panic is a postprocessor for FITS mosaic files that have been generated by GEIRS.

6.10.2 Function Documentation

6.10.2.1 void usage (char * argv0, int gap, int chpsz, double north)

Print a usage syntax message detailing the command line.

Parameters

<code>in</code>	<code>argv0</code>	The name of the main program.
-----------------	--------------------	-------------------------------

Since

2012-10-18

6.10.2.2 `int main (int argc, char * argv[])`

The program is a postprocessor for FITS files of CAHA/PANIC that have been generated by GEIRS.

The main and mandatory arguments are an existing FITS file of the 2x2 mosaic in the glued representation as generated by GEIRS, and the name of a non-existing FITS file that will be generated by the program.

The program supports

- insertion of a cross of undefined values in the mosaic, the definition of the North direction in the image and associated flip/rotation by multiples of 90 degrees to align that direction as good as possible with the up-direction in the image, plus insertion of the linear WCS scale transformation.

- insertion of ALT, AZ and PARANG angles in the output header.

- insertion of OBSGEO-X, OBSGEO-Y and OBSGEO-Z in the output header.

Note that in a field of view stretching across 1 deg, the atmospheric dispersion $R = \tan(z) * (n-1)$ (in radians) differs across the field by $\Delta(R) = \Delta(z) / \cos^2(z) * (n-1)$, where $n-1=2e-4$ is roughly the index of refraction at the mountain altitude of 2700 m. Since $\Delta(z)$ is roughly 4000 pixels, the product of both factors amounts to roughly 1 pixel across the field, but that expected linear distortion is not yet included in the WCS keywords of the header in the output.

All of these tasks are actually covered by the instrument pipeline (Ibanez-Menguál et al, "The PANIC software system", SPIE 77402E, July 19 2012, doi:10.1117/12.856029) and do not need to be run on the mountain.

Parameters

in	<i>argc</i>	The number of command line switches and arguments.
in	<i>argv</i>	<p>The vector of all command line arguments. The standard syntax is <code>geirs2Panic [-c chipsz] [-g gapPx] [-A] [-t] [-f] [-N degr] [-v] fitsIn [fitsOut.fits]</code> The options and their arguments are:</p> <ul style="list-style-type: none"> • <code>-c chipsz</code> Sets the edge length of the single chip in the mosaic in units of pixels. This defines the regular distance at which gaps appear in the mosaic. The current default size is 2048. CAHA/LAICA users should set this to 4096. • <code>-g gapPx</code> This is the gap between any two chips in the mosaic, in units of pixels. There is a default which is some value of the literature, currently 167. CAHA/LAICA users should set this to 3207 (assuming a pixel scale of 0.225 arcsec/px and 2 times 100 arcsec overlap of the gap with the two adjacent chips). • <code>-A</code> Requests that the ALT, AZ and PARANG values are inserted into the header (or replaced if they exist). This uses standard spherical trigonometry and assumes that the latitude, hour angle and declination are all given in degrees in the FITS header. The latitude may either be TELLAT (preferred is the standard OBSGEO-B) and the other two are taken from HA and DEC in the FITS header. • <code>-t</code> Replaces the 4 pixels around each chip of the mosaic by the BLANK value. This is useful to avoid confusion of standard pipeline code that does not know how to interpret these engineering pixels. • <code>-N degr</code> Indicates that North is that many degrees in counter-clockwise position from the horizontal axis in the input image. So a value near +90 would be about ideal. This has two implications: The WCS sky transformation will have the correct entries, and values more than 45 degrees away from 90 will trigger a rotation by multiples of 90 degrees on output. • <code>-f</code> Indicates that East is on the wrong side of North in the input data. This triggers that an additional flip (alongside any rotations) of the images is done for the output. Note that this is associated with a flip of North and additional changes of the WCS matrix. • <code>-G</code> Triggers that the OBSGEO-X OBSGEO-Y OBSGEO-Z triple is added to the header on output. This works only if the three TELLONG TELLAT and TELALT or their standard OBSGEO-B, OBSGEO-L and OBSGEO-H values with are provided in the standard units in the input header. • <code>-v</code> generates more comments on standard output about what the program is doing. • <code>fitsIn</code> is either (i) a single file with suffix <code>.fits</code> which contains either a full frame or a subwindow of the mosaic, or (ii) a basis name for a set of GEIRS window files without their <code>_wini<code>.fits</code> parts. Note that any of these windows may already stretch across more than one of the chips of the mosaic, because GEIRS uses windowing in that manner. • <code>fitsOut.fits</code> is an optional file name with suffix <code>.fits</code> to be chosen for the output file. If this final argument is absent, the program chooses a file name which is the concatenation of the instrument name (keyword INSTRUME) and date, keyword DATE-OBS (preferred) or DATE.

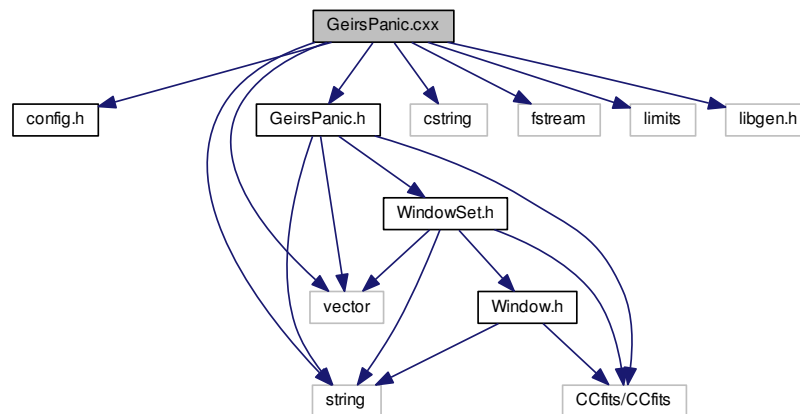
Since

2012-10-23

6.11 GeirsPanic.cxx File Reference

```
#include "config.h"  
#include "GeirsPanic.h"  
#include <string>  
#include <cstring>  
#include <vector>  
#include <fstream>  
#include <limits>  
#include <libgen.h>
```

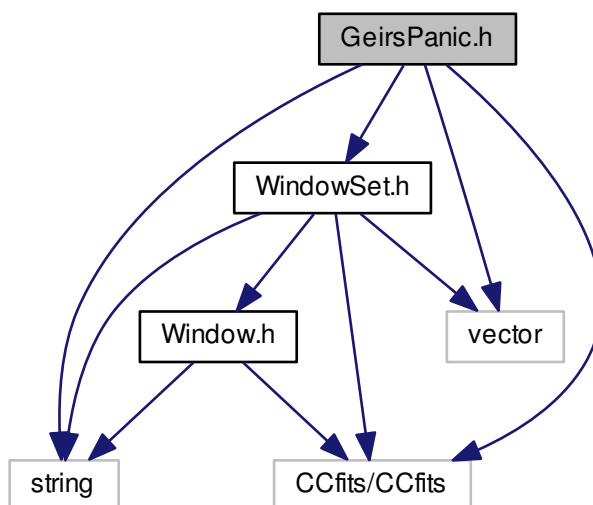
Include dependency graph for GeirsPanic.cxx:



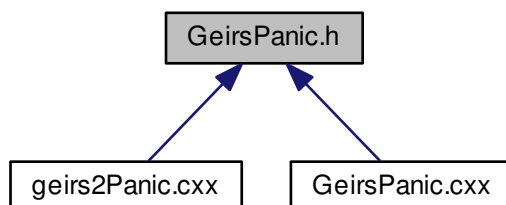
6.12 GeirsPanic.h File Reference

```
#include <string>  
#include <vector>  
#include <CCfits/CCfits>  
#include "WindowSet.h"
```

Include dependency graph for GeirsPanic.h:



This graph shows which files directly or indirectly include this file:



Classes

- class [GeirsPanic](#)

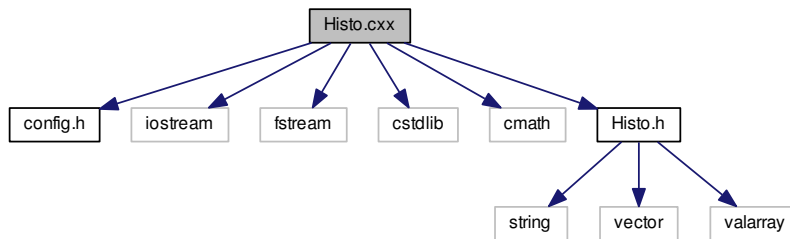
6.13 Histo.cxx File Reference

```

#include "config.h"
#include <iostream>
#include <fstream>
#include <cstdlib>
#include <cmath>
#include "Histo.h"

```

Include dependency graph for Histo.cxx:



Functions

- int `fsort` (const void *v1, const void *v2)
Support of the `qsort` call in `init()`.

6.13.1 Function Documentation

6.13.1.1 int `fsort` (const void * v1, const void * v2)

Support of the `qsort` call in `init()`.

Parameters

<code>v1</code>	The first constant to be compared.
<code>v2</code>	The second constant to be compared.

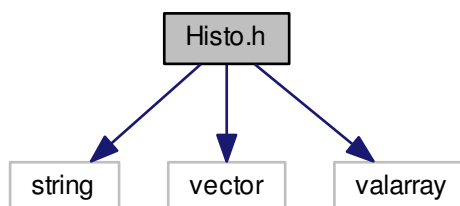
Returns

-1 if `v1` is less than `v2`, +1 if `v1` is larger than `v2`, 0 if both are equal.

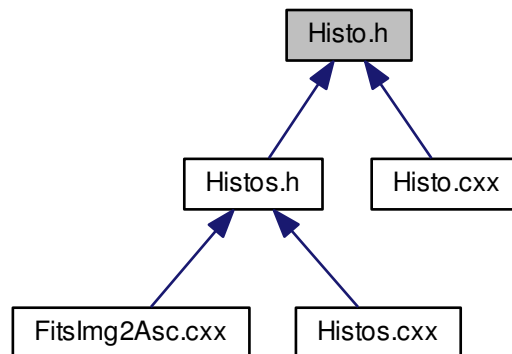
6.14 Histo.h File Reference

```

#include <string>
#include <vector>
#include <valarray>
Include dependency graph for Histo.h:
  
```



This graph shows which files directly or indirectly include this file:



Classes

- class [Histo](#)

Functions

- int [fsort](#) (const void *v1, const void *v2)
Support of the qsort call in `init()`.

6.14.1 Function Documentation

6.14.1.1 int fsort (const void * v1, const void * v2)

Support of the qsort call in `init()`.

Parameters

v1	The first constant to be compared.
v2	The second constant to be compared.

Returns

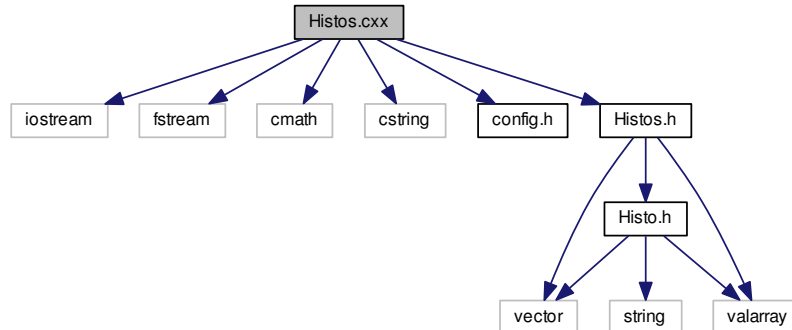
-1 if v1 is less than v2, +1 if v1 is larger than v2, 0 if both are equal.

6.15 Histos.cxx File Reference

```

#include <iostream>
#include <fstream>
#include <cmath>
#include <cstring>
#include "config.h"
#include "Histos.h"
  
```

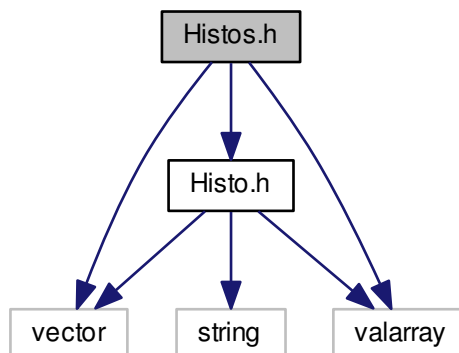
Include dependency graph for Histos.cxx:



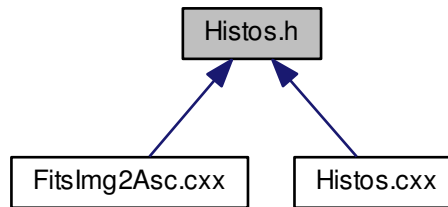
6.16 Histos.h File Reference

```
#include <vector>
#include <valarray>
#include "Histo.h"
```

Include dependency graph for Histos.h:



This graph shows which files directly or indirectly include this file:



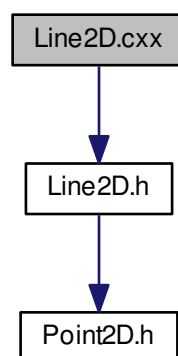
Classes

- class [Histos](#)

6.17 Line2D.cxx File Reference

```
#include "Line2D.h"
```

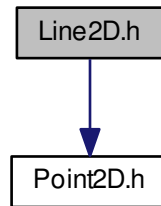
Include dependency graph for Line2D.cxx:



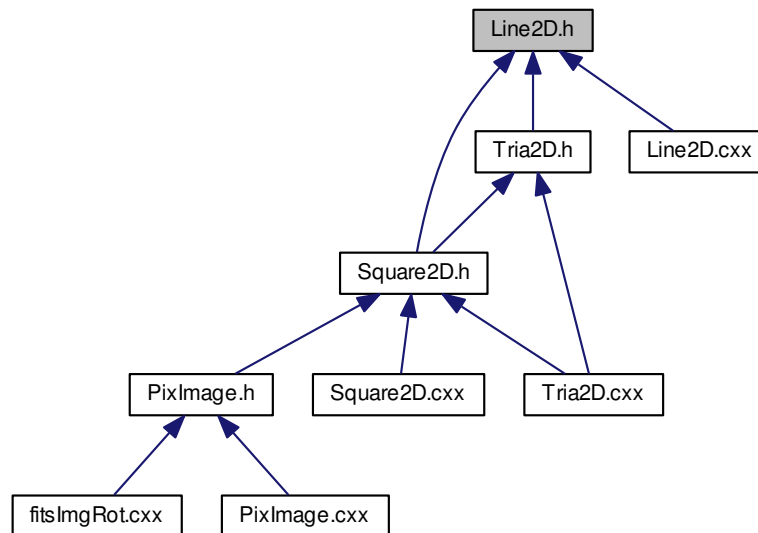
6.18 Line2D.h File Reference

```
#include "Point2D.h"
```

Include dependency graph for Line2D.h:



This graph shows which files directly or indirectly include this file:



Classes

- class [Line2D](#)

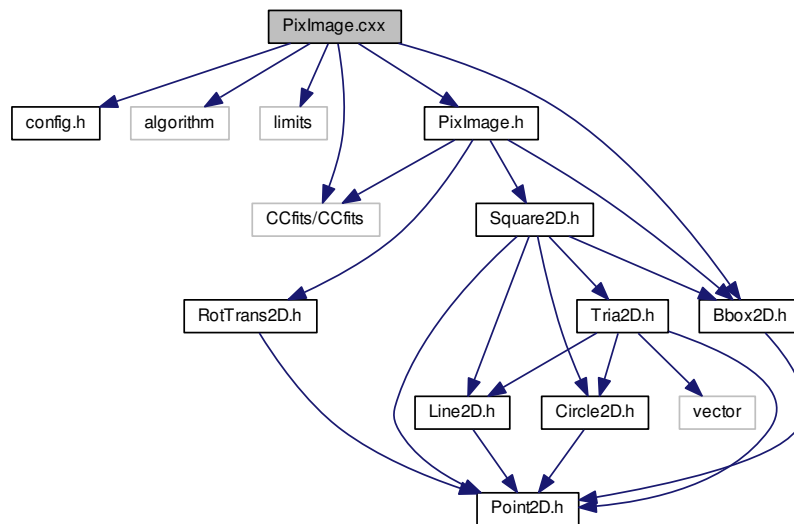
An oriented line section represented by the 2-dimensional coordinates of starting and terminating point.

6.19 PixImage.cxx File Reference

```

#include "config.h"
#include <algorithm>
#include <limits>
#include <CCfits/CCfits>
#include "PixImage.h"
#include "Bbox2D.h"
  
```

Include dependency graph for PixImage.cxx:



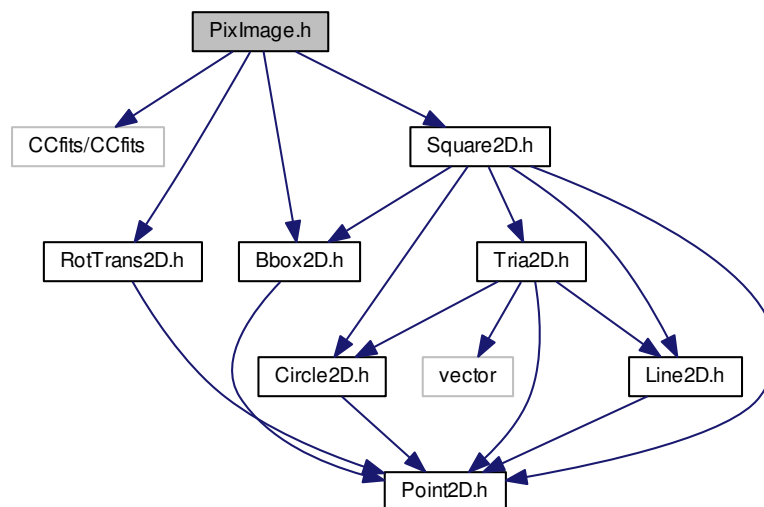
6.20 PixImage.h File Reference

```

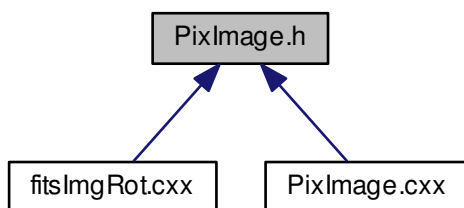
#include <CCfits/CCfits>
#include "RotTrans2D.h"
#include "Bbox2D.h"
#include "Square2D.h"

```

Include dependency graph for PixImage.h:



This graph shows which files directly or indirectly include this file:



Classes

- class [PixImage](#)

A rectangular 2-dimensional array of pixels with individual values.

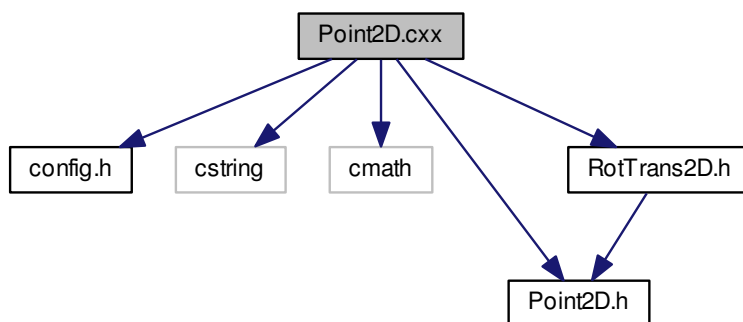
6.21 Point2D.cxx File Reference

```

#include "config.h"
#include <cstring>
#include <cmath>
#include "Point2D.h"
#include "RotTrans2D.h"

```

Include dependency graph for `Point2D.cxx`:



Functions

- `Point2D operator+` (const `Point2D` &left, const `Point2D` &right)

Add two points, interpreting both points as vectors.

6.21.1 Function Documentation

6.21.1.1 Point2D operator+ (const Point2D & *left*, const Point2D & *right*)

Add two points, interpreting both points as vectors.

Parameters

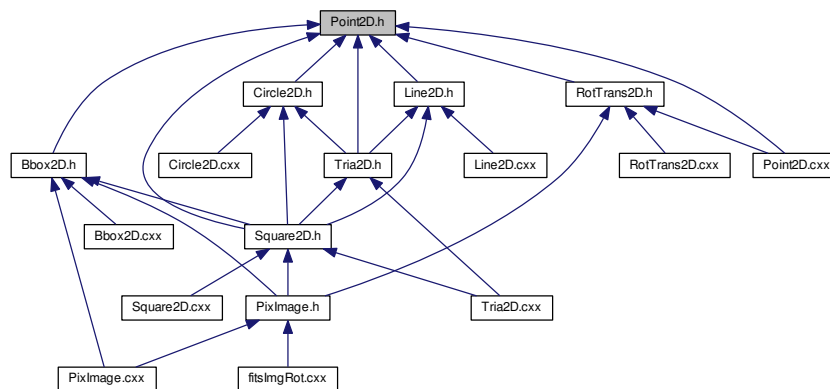
<i>left</i>	The point to the left of the + sign.
<i>right</i>	The point to right of the + sign.

Returns

A point with coordinates that are sums of coordinates of both arguments.

6.22 Point2D.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

- class [Point2D](#)

A point with 2 coordinates represented in a Cartesian coordinate system.

Functions

- [Point2D operator+](#) (const [Point2D](#) &left, const [Point2D](#) &right)

Add two points, interpreting both points as vectors.

6.22.1 Function Documentation

6.22.1.1 Point2D operator+ (const Point2D & left, const Point2D & right)

Add two points, interpreting both points as vectors.

Parameters

<i>left</i>	The point to the left of the + sign.
<i>right</i>	The point to right of the + sign.

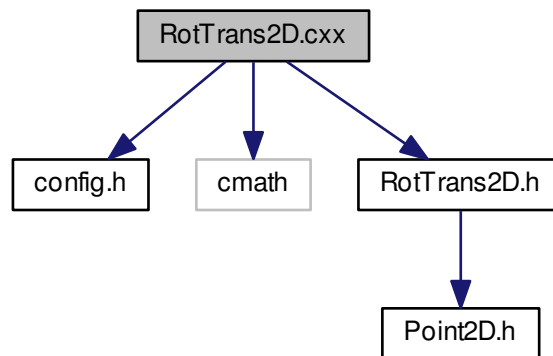
Returns

A point with coordinates that are sums of coordinates of both arguments.

6.23 RotTrans2D.cxx File Reference

```
#include "config.h"  
#include <cmath>  
#include "RotTrans2D.h"
```

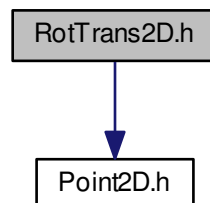
Include dependency graph for RotTrans2D.cxx:



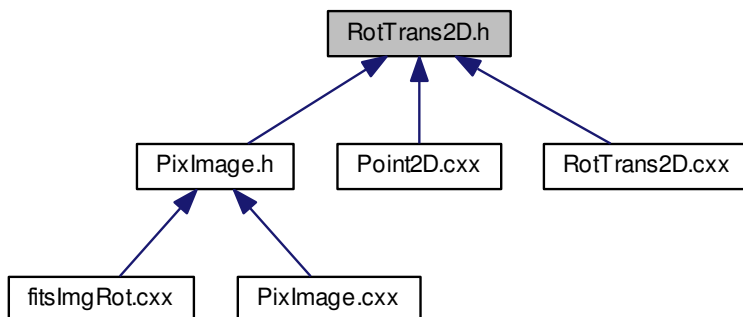
6.24 RotTrans2D.h File Reference

```
#include "Point2D.h"
```

Include dependency graph for RotTrans2D.h:



This graph shows which files directly or indirectly include this file:



Classes

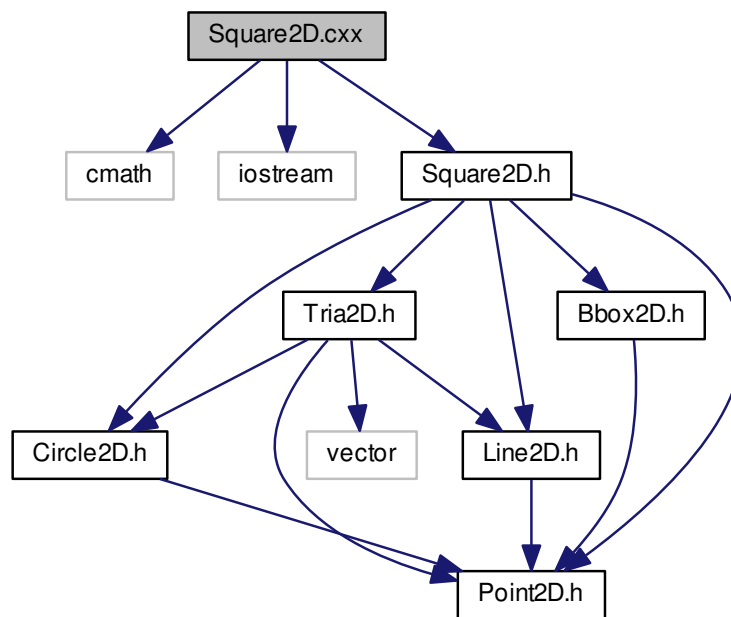
- class [RotTrans2D](#)

A rotation followed by a translation.

6.25 Square2D.cxx File Reference

```
#include <cmath>
#include <iostream>
#include "Square2D.h"
```

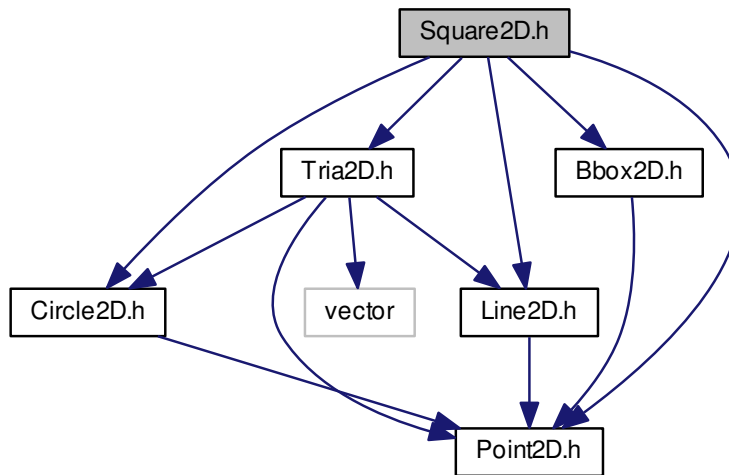
Include dependency graph for Square2D.cxx:



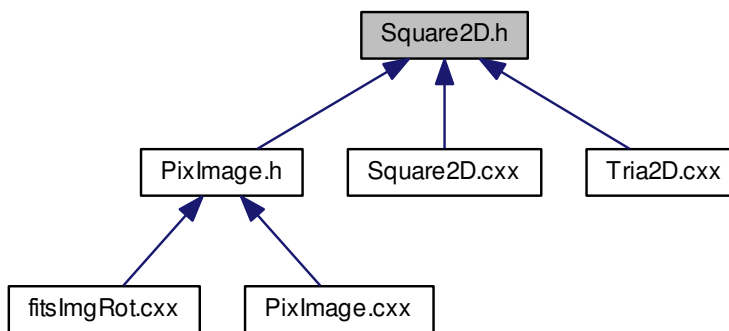
6.26 Square2D.h File Reference

```
#include "Point2D.h"  
#include "Line2D.h"  
#include "Circle2D.h"  
#include "Tria2D.h"  
#include "Bbox2D.h"
```

Include dependency graph for Square2D.h:



This graph shows which files directly or indirectly include this file:



Classes

- class [Square2D](#)

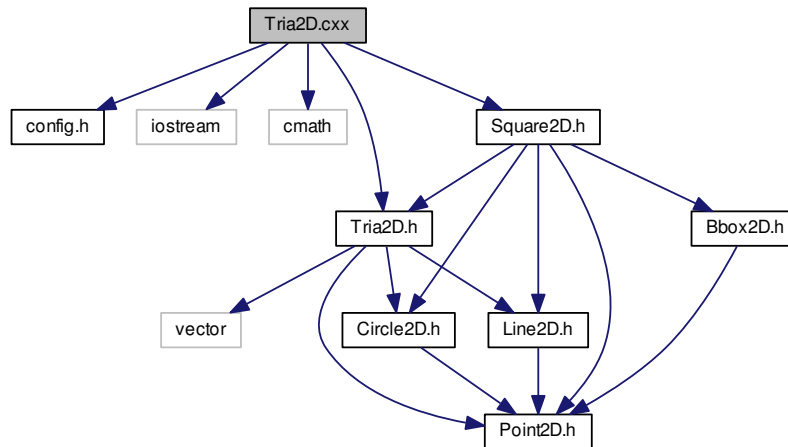
A square represented by the four vertices of the corners.

6.27 Tria2D.cxx File Reference

```
#include "config.h"
```

```
#include <iostream>
#include <cmath>
#include "Tria2D.h"
#include "Square2D.h"
```

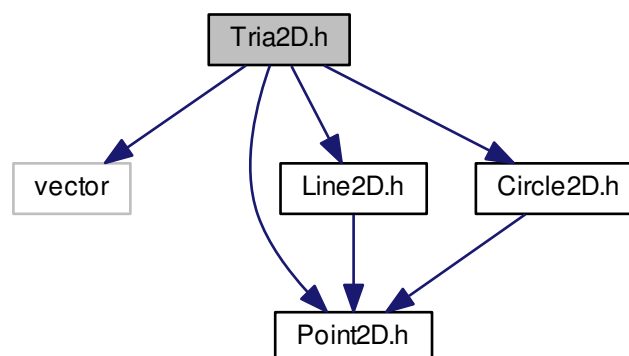
Include dependency graph for Tria2D.cxx:



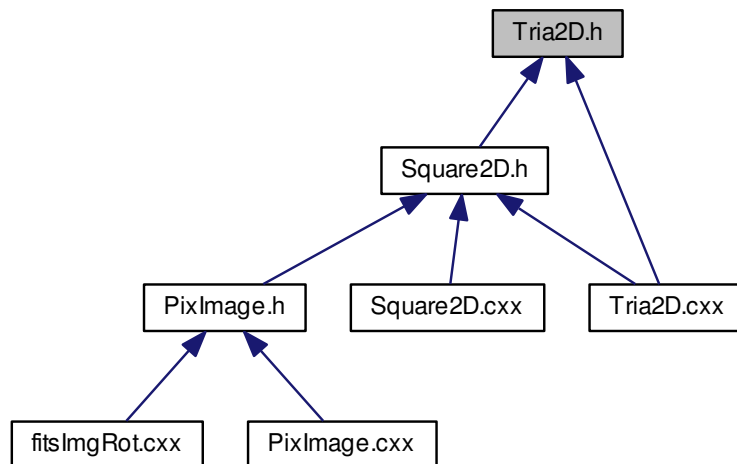
6.28 Tria2D.h File Reference

```
#include <vector>
#include "Point2D.h"
#include "Line2D.h"
#include "Circle2D.h"
```

Include dependency graph for Tria2D.h:



This graph shows which files directly or indirectly include this file:



Classes

- class `Tria2D`

A triangle represented by the Cartesian coordinates of its three vertices.

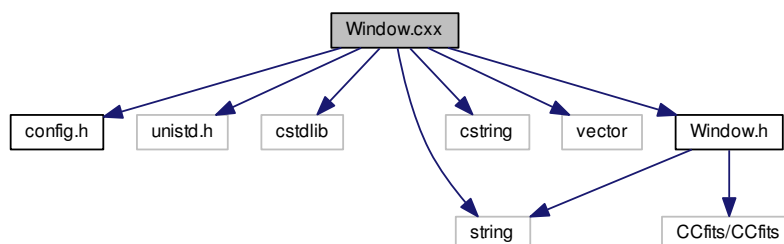
6.29 Window.cxx File Reference

```

#include "config.h"
#include <unistd.h>
#include <cstdlib>
#include <string>
#include <cstring>
#include <vector>
#include "Window.h"

```

Include dependency graph for `Window.cxx`:



Macros

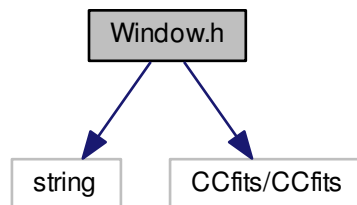
- `#define GEIRS2PANIC_WINDOW_TRIM`

6.29.1 Macro Definition Documentation

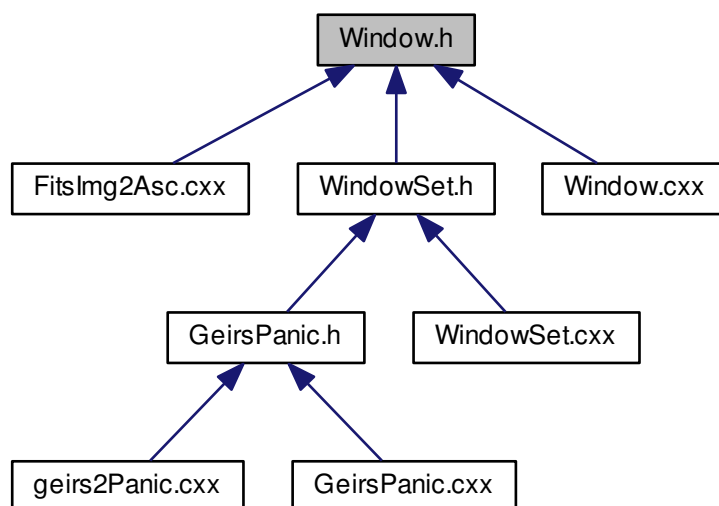
6.29.1.1 `#define GEIRS2PANIC_WINDOW_TRIM`

6.30 Window.h File Reference

```
#include <string>
#include <CCfits/CCfits>
Include dependency graph for Window.h:
```



This graph shows which files directly or indirectly include this file:



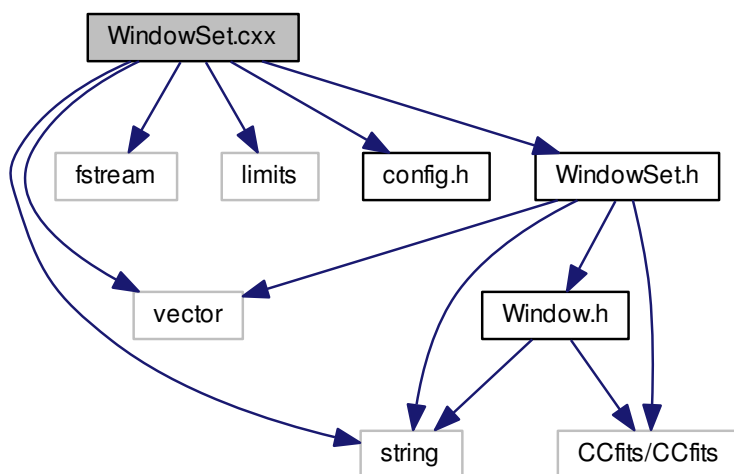
Classes

- class [Window](#)

6.31 WindowSet.cxx File Reference

```
#include <string>
#include <vector>
#include <fstream>
#include <limits>
#include "config.h"
#include "WindowSet.h"
```

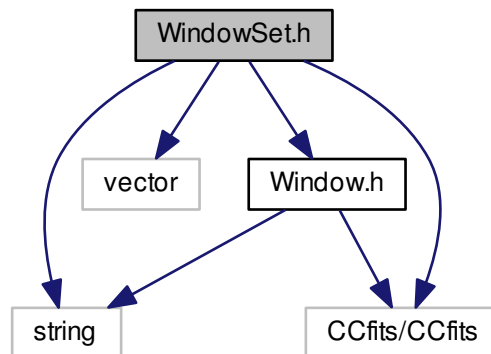
Include dependency graph for WindowSet.cxx:



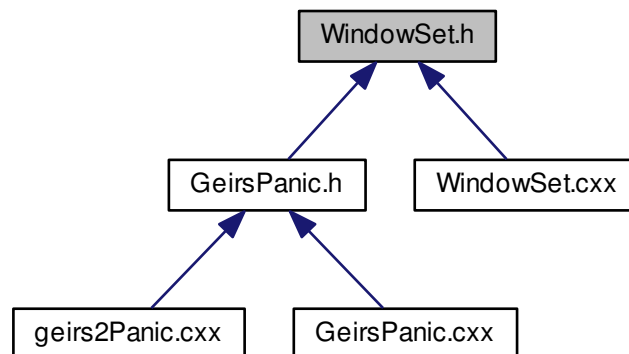
6.32 WindowSet.h File Reference

```
#include <string>
#include <vector>
#include <CCfits/CCfits>
#include "Window.h"
```


Include dependency graph for WindowSet.h:



This graph shows which files directly or indirectly include this file:



Classes

- class [WindowSet](#)

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